

Solutionbank M5

Edexcel AS and A Level Modular Mathematics

Exercise A, Question 1

Question:

At time t seconds the position vector of a particle P is \mathbf{r} metres and its velocity is $\mathbf{v} \text{ m s}^{-1}$. The motion of P is modelled by the differential equation

$$\frac{d\mathbf{v}}{dt} = 3\mathbf{v}.$$

Given that when $t = 0$, $\mathbf{r} = 3\mathbf{i}$ and $\mathbf{v} = \mathbf{i} - \mathbf{j}$, find \mathbf{r} in terms of t .

Solution:

$$\frac{dv}{dt} - 3v = 0 \quad \text{Auxiliary equation is } \lambda - 3 = 0$$

$$\Rightarrow \lambda = 3$$

General solution is $v = Ae^{3t}$

When $t = 0, v = i - j \Rightarrow i - j = A$

So, $v = (i - j)e^{3t}$

$$\text{i.e. } \frac{dr}{dt} = (i - j)e^{3t}$$

$$\Rightarrow r = \frac{1}{3}(i - j)e^{3t} + B$$

$$\text{When } t = 0, r = 3i \Rightarrow 3i = \frac{1}{3}(i - j) + B$$

$$\Rightarrow \frac{8}{3}i + \frac{1}{3}j = B$$

$$\text{Hence, } r = \frac{1}{3}(i - j)e^{3t} + \frac{8}{3}i + \frac{1}{3}j$$

$$= \frac{1}{3}\{e^{3t} + 8\}i + \frac{1}{3}\{1 - e^{3t}\}j$$

Alternative method

$$\frac{dv}{dt} - 3v = 0$$

$$\Rightarrow \frac{d^2r}{dt^2} - 3\frac{dr}{dt} = 0$$

Auxiliary equation:

$$\lambda^2 - 3\lambda = 0 \Rightarrow \lambda(\lambda - 3) = 0$$

$$\Rightarrow \lambda = 0 \text{ or } 3$$

\Rightarrow General Solution is $v = A + Be^{3t}$

$$t = 0, r = 3i \Rightarrow 3i = A + B \quad \textcircled{1}$$

$$r = A + Be^{3t} \Rightarrow v = 3Be^{3t}$$

$$t = 0, v = i - j \Rightarrow i - j = 3B$$

$$\Rightarrow \frac{1}{3}(i - j) = B$$

Substitute into ①

$$A = \frac{8}{3}i + \frac{1}{3}j$$

$$\text{Hence, } r = \frac{8}{3}i + \frac{1}{3}j + \frac{1}{3}(i - j)e^{3t} \quad \text{as before}$$

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Exercise A, Question 2

Question:

The velocity $\mathbf{v} \text{ m s}^{-1}$ of a particle P at time t seconds satisfies the differential equation

$$\frac{d\mathbf{v}}{dt} + \mathbf{v} = \mathbf{0}.$$

Given that the initial velocity of P is $(12\mathbf{i} + 6\mathbf{j})$, find the velocity of P at $t = \ln 3$.

Solution:

$$\frac{d\mathbf{v}}{dt} + \mathbf{v} = \mathbf{0} \Rightarrow \lambda + 1 = 0 \Rightarrow \lambda = -1$$

So, general solution is $\mathbf{v} = \mathbf{A}e^{-t}$

$$t = 0, \mathbf{v} = 12\mathbf{i} + 6\mathbf{j} \Rightarrow \mathbf{v} = (12\mathbf{i} + 6\mathbf{j})e^{-t}$$

$$\begin{aligned} \text{When } t = \ln 3, \quad \mathbf{v} &= (12\mathbf{i} + 6\mathbf{j})e^{-\ln 3} \\ &= 4\mathbf{i} + 2\mathbf{j} \end{aligned}$$

Velocity is $(4\mathbf{i} + 2\mathbf{j}) \text{ m s}^{-1}$

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Exercise A, Question 3

Question:

The velocity $\mathbf{v} \text{ m s}^{-1}$ at time t seconds of a particle moving in a plane satisfies the differential equation

$$\frac{d\mathbf{v}}{dt} = 6\mathbf{v}, \text{ where } \mathbf{v} = 4\mathbf{i} + 2\mathbf{j} \text{ when } t = 0.$$

Given that the particle starts, at $t = 0$, at the point with position vector $(\mathbf{i} + \mathbf{j})\text{m}$ find

- the position vector of the particle P at time t seconds,
- the time when the magnitude of the acceleration of the particle P first equals 100 m s^{-2} .

Solution:

$$\frac{d\mathbf{v}}{dt} - 6\mathbf{v} = \mathbf{0} \Rightarrow \lambda - 6 = 0 \Rightarrow \lambda = 6$$

So, general solution is $\mathbf{v} = \mathbf{A}e^{6t}$

$$t = 0, \mathbf{v} = 4\mathbf{i} + 2\mathbf{j} \Rightarrow \mathbf{v} = (4\mathbf{i} + 2\mathbf{j})e^{6t}$$

$$\Rightarrow \mathbf{r} = \frac{1}{6}(4\mathbf{i} + 2\mathbf{j})e^{6t} + \mathbf{B}$$

$$t = 0, \mathbf{r} = \mathbf{i} + \mathbf{j} \Rightarrow \mathbf{i} + \mathbf{j} = \frac{1}{6}(4\mathbf{i} + 2\mathbf{j}) + \mathbf{B}$$

$$\Rightarrow \frac{1}{3}\mathbf{i} + \frac{2}{3}\mathbf{j} = \mathbf{B}$$

$$\text{a Hence, } \mathbf{r} = \frac{1}{3}(2\mathbf{i} + \mathbf{j})e^{6t} + \frac{1}{3}\mathbf{i} + \frac{2}{3}\mathbf{j}$$

$$\text{b } \mathbf{a} = \frac{d\mathbf{v}}{dt} = 6\mathbf{v} = (24\mathbf{i} + 12\mathbf{j})e^{6t} \\ = 12e^{6t}(2\mathbf{i} + \mathbf{j})$$

$$|\mathbf{a}| = 12e^{6t}\sqrt{2^2 + 1^2}$$

$$= 12\sqrt{5}e^{6t}$$

$$\text{So, } 12\sqrt{5}e^{6t} = 100$$

$$\Rightarrow t = \frac{1}{6}\ln\left(\frac{100}{12\sqrt{5}}\right) = 0.2195 \quad (3 \text{ s.f.})$$

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Exercise A, Question 4

Question:

At time t seconds the position vector of a particle P is \mathbf{r} metres and its velocity is $\mathbf{v} \text{ m s}^{-1}$. The motion of P is described by the differential equation

$$\frac{d\mathbf{v}}{dt} = 4\mathbf{v}.$$

Given that when $t = 0$, $\mathbf{r} = \mathbf{i} - \mathbf{k}$ and $\mathbf{v} = \mathbf{i} + \mathbf{j} + \mathbf{k}$,

- find \mathbf{r} in terms of t ,
- find the speed of P when $t = 2$,
- find the magnitude of the acceleration of P when $t = 2$.

Solution:

$$\frac{d\mathbf{v}}{dt} - 4\mathbf{v} = \mathbf{0} \Rightarrow \frac{d^2\mathbf{r}}{dt^2} - 4\frac{d\mathbf{r}}{dt} = \mathbf{0} \Rightarrow \lambda^2 - 4\lambda = 0$$

$$\Rightarrow \lambda = 0 \text{ or } 4$$

So, general solution is $\mathbf{r} = \mathbf{A} + \mathbf{B}e^{4t}$

$$\text{a } t = 0, \mathbf{r} = \mathbf{i} - \mathbf{k} \Rightarrow \mathbf{i} - \mathbf{k} = \mathbf{A} + \mathbf{B} \quad \text{①}$$

$$\mathbf{v} = 4\mathbf{B}e^{4t}; t = 0, \mathbf{v} = \mathbf{i} + \mathbf{j} + \mathbf{k} \Rightarrow \mathbf{B} = \frac{1}{4}(\mathbf{i} + \mathbf{j} + \mathbf{k})$$

$$\Rightarrow \mathbf{A} = \mathbf{i} - \mathbf{k} - \frac{1}{4}(\mathbf{i} + \mathbf{j} + \mathbf{k})$$

$$= \frac{3}{4}\mathbf{i} - \frac{1}{4}\mathbf{j} - \frac{5}{4}\mathbf{k} = \frac{1}{4}(3\mathbf{i} - \mathbf{j} - 5\mathbf{k})$$

$$\text{So, } \mathbf{r} = \frac{1}{4}\{3\mathbf{i} - \mathbf{j} - 5\mathbf{k} + (\mathbf{i} + \mathbf{j} + \mathbf{k})e^{4t}\}$$

$$\text{b } \mathbf{v} = (\mathbf{i} + \mathbf{j} + \mathbf{k})e^{4t}$$

$$\text{When } t = 2, \mathbf{v} = (\mathbf{i} + \mathbf{j} + \mathbf{k})e^8$$

$$|\mathbf{v}| = e^8\sqrt{3} \text{ m s}^{-1}$$

$$\text{c As } \mathbf{a} = \frac{d\mathbf{v}}{dt} = 4\mathbf{v}$$

$$\text{At } t = 2, |\mathbf{a}| = 4e^8\sqrt{3} \text{ m s}^{-2}$$

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Exercise A, Question 5

Question:

At time t seconds the position vector of a particle P is \mathbf{r} metres. The motion of P is described by the differential equation

$$\frac{d^2\mathbf{r}}{dt^2} = 2\frac{d\mathbf{r}}{dt}.$$

Given that the initial velocity of P is $(2\mathbf{i} - \mathbf{j})\text{ m s}^{-1}$, find the speed of P at $t = \ln 3$.

Solution:

$$\frac{d^2\mathbf{r}}{dt^2} - 2\frac{d\mathbf{r}}{dt} = \mathbf{0} \Rightarrow \frac{d\mathbf{v}}{dt} - 2\mathbf{v} = \mathbf{0}$$

$$\Rightarrow \lambda - 2 = 0 \Rightarrow \lambda = 2$$

$$\Rightarrow \mathbf{v} = \mathbf{A}e^{2t}$$

$$t = 0, \mathbf{v} = 2\mathbf{i} - \mathbf{j} \Rightarrow \mathbf{v} = (2\mathbf{i} - \mathbf{j})e^{2t}$$

$$t = \ln 3, \quad \mathbf{v} = (2\mathbf{i} - \mathbf{j})e^{2\ln 3} \\ = (18\mathbf{i} - 9\mathbf{j})$$

$$\therefore |\mathbf{v}| = 9\sqrt{2^2 + (-1)^2} = 9\sqrt{5} \text{ m s}^{-1}$$

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Exercise A, Question 6

Question:

At time t seconds the position vector of a particle P is \mathbf{r} metres. The motion of P is modelled by the differential equation

$$\frac{d\mathbf{r}}{dt} + 2\mathbf{r} = (15\mathbf{i} + 10\mathbf{j})e^{3t}.$$

Given that when $t = 0$, $\mathbf{r} = 2\mathbf{i} + \mathbf{j}$, find

a \mathbf{r} in terms of t ,

b the velocity of P when $t = \ln 4$.

Solution:

$$\mathbf{a} \quad \frac{d\mathbf{r}}{dt} + 2\mathbf{r} = \begin{pmatrix} 15 \\ 10 \end{pmatrix} e^{3t}$$

$$\text{Integrating factor} = e^{\int 2dt} = e^{2t}$$

$$\frac{d}{dt}(e^{2t}\mathbf{r}) = \begin{pmatrix} 15 \\ 10 \end{pmatrix} e^{5t}$$

$$e^{2t}\mathbf{r} = \begin{pmatrix} 3 \\ 2 \end{pmatrix} e^{5t} + \mathbf{C}$$

$$t = 0, \mathbf{r} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} \Rightarrow \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 3 \\ 2 \end{pmatrix} + \mathbf{C} \Rightarrow \mathbf{C} = \begin{pmatrix} -1 \\ -1 \end{pmatrix}$$

$$\mathbf{r} = \begin{pmatrix} 3 \\ 2 \end{pmatrix} e^{3t} + \begin{pmatrix} -1 \\ -1 \end{pmatrix} e^{-2t}$$

$$\mathbf{b} \quad \mathbf{v} = \begin{pmatrix} 9 \\ 6 \end{pmatrix} e^{3t} + \begin{pmatrix} 2 \\ 2 \end{pmatrix} e^{-2t}$$

$$t = \ln 4, \mathbf{v} = \begin{pmatrix} 9 \\ 6 \end{pmatrix} \times 64 + \begin{pmatrix} 2 \\ 2 \end{pmatrix} \times \frac{1}{16} = \begin{pmatrix} 576\frac{1}{8} \\ 384\frac{1}{8} \end{pmatrix}$$

$$\text{velocity is } (576\frac{1}{8}\mathbf{i} + 384\frac{1}{8}\mathbf{j}) \text{ m s}^{-1}$$

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Exercise A, Question 7

Question:

The position vector \mathbf{r} metres of a particle P at time t seconds satisfies the vector differential equation

$$\frac{d\mathbf{r}}{dt} + \mathbf{r} = \mathbf{k}e^t.$$

Given that when $t = 0$, $\mathbf{r} = 2\mathbf{i} + 3\mathbf{j} + \mathbf{k}$ find \mathbf{r} in terms of t .

Solution:

$$\frac{d\mathbf{r}}{dt} + \mathbf{r} = \mathbf{k}e^t$$

Integrating factor $= e^{\int 1 dt} = e^t$

$$\Rightarrow \frac{d}{dt}(\mathbf{r}e^t) = \mathbf{k}e^{2t}$$

$$\Rightarrow \mathbf{r}e^t = \int \mathbf{k}e^{2t} dt = \frac{1}{2}\mathbf{k}e^{2t} + \mathbf{c}$$

When $t = 0$, $\mathbf{r} = 2\mathbf{i} + 3\mathbf{j} + \mathbf{k}$

$$\Rightarrow (2\mathbf{i} + 3\mathbf{j} + \mathbf{k}) = \frac{1}{2}\mathbf{k} + \mathbf{c}$$

$$\Rightarrow 2\mathbf{i} + 3\mathbf{j} + \frac{1}{2}\mathbf{k} = \mathbf{c}$$

$$\Rightarrow \mathbf{r} = \frac{1}{2}\mathbf{k}e^t + (2\mathbf{i} + 3\mathbf{j} + \frac{1}{2}\mathbf{k})e^{-t}$$

$$\mathbf{r} = 2e^{-t}\mathbf{i} + 3e^{-t}\mathbf{j} + \frac{1}{2}(e^t + e^{-t})\mathbf{k}$$

Alternative method

$$\frac{d\mathbf{r}}{dt} + \mathbf{r} = \mathbf{0} \Rightarrow \lambda + 1 = 0 \Rightarrow \lambda = -1$$

C.F. is $\mathbf{r} = \mathbf{A}e^{-t}$

$$\text{P.I. Try } \mathbf{r} = \mathbf{B}e^t \Rightarrow \frac{d\mathbf{r}}{dt} = \mathbf{B}e^t$$

$$\text{So, } \mathbf{B}e^t + \mathbf{B}e^t = \mathbf{k}e^t \Rightarrow \mathbf{B} = \frac{1}{2}\mathbf{k}$$

$$\text{So P.I. is } \mathbf{r} = \frac{1}{2}\mathbf{k}e^t$$

General solution is C.F. + P.I.

$$\text{i.e. } \mathbf{r} = \mathbf{A}e^{-t} + \frac{1}{2}\mathbf{k}e^t$$

$$t = 0, \mathbf{r} = 2\mathbf{i} + 3\mathbf{j} + \mathbf{k} \Rightarrow 2\mathbf{i} + 3\mathbf{j} + \mathbf{k} = \mathbf{A} + \frac{1}{2}\mathbf{k}$$

$$\Rightarrow 2\mathbf{i} + 3\mathbf{j} + \frac{1}{2}\mathbf{k} = \mathbf{A}$$

$$\text{So, } \mathbf{r} = (2\mathbf{i} + 3\mathbf{j} + \frac{1}{2}\mathbf{k})e^{-t} + \frac{1}{2}\mathbf{k}e^t \quad \text{as before}$$

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Exercise A, Question 8

Question:

At time t the velocity \mathbf{v} of a particle P satisfies the vector differential equation $\frac{d\mathbf{v}}{dt} + \frac{3\mathbf{v}}{T} = \mathbf{0}$, where T is a constant.

At time $t = 0$ the position vector of P is $a(2\mathbf{i} + \mathbf{j})$ and its velocity is $\frac{3a(\mathbf{i} - \mathbf{j})}{T}$.

Find the position vector of P at time t .

Solution:

$$\frac{d\mathbf{v}}{dt} + \frac{3}{T}\mathbf{v} = \mathbf{0} \Rightarrow \lambda + \frac{3}{T} = 0$$

$$\Rightarrow \lambda = -\frac{3}{T}$$

$$\therefore \mathbf{v} = \mathbf{A}e^{-\frac{3t}{T}}$$

$$\Rightarrow \mathbf{r} = -\frac{T}{3}\mathbf{A}e^{-\frac{3t}{T}} + \mathbf{B}$$

$$\text{When } t = 0, \mathbf{v} = \frac{3a}{T}(\mathbf{i} - \mathbf{j}) \Rightarrow \frac{3a}{T}(\mathbf{i} - \mathbf{j}) = \mathbf{A}$$

$$\text{So, } \mathbf{r} = -a(\mathbf{i} - \mathbf{j})e^{-\frac{3t}{T}} + \mathbf{B}$$

$$\text{When } t = 0, \mathbf{r} = a(2\mathbf{i} + \mathbf{j})$$

$$\Rightarrow a(2\mathbf{i} + \mathbf{j}) = -a(\mathbf{i} - \mathbf{j}) + \mathbf{B}$$

$$\Rightarrow a(3\mathbf{i}) = \mathbf{B}$$

$$\text{So, } \mathbf{r} = 3a\mathbf{i} - a(\mathbf{i} - \mathbf{j})e^{-\frac{3t}{T}}$$

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Exercise A, Question 9

Question:

The position vector of a particle P at time t seconds is \mathbf{r} metres. The motion of P is modelled by the vector differential equation

$$\frac{d\mathbf{r}}{dt} + 3\mathbf{r} = 4e^{-t}\mathbf{j}.$$

Given that when $t = 0$, $\mathbf{r} = 2\mathbf{i} - \mathbf{j}$, find \mathbf{r} in terms of t .

Solution:

$$\frac{d\mathbf{r}}{dt} + 3\mathbf{r} = 4e^{-t}\mathbf{j} \quad \text{I.F.} = e^{\int 3dt} = e^{3t}$$

$$\Rightarrow \frac{d}{dt}(\mathbf{r}e^{3t}) = 4e^{2t}\mathbf{j}$$

$$\mathbf{r}e^{3t} = 2e^{2t}\mathbf{j} + \mathbf{A}$$

$$t = 0, \mathbf{r} = 2\mathbf{i} - \mathbf{j} \Rightarrow 2\mathbf{i} - \mathbf{j} = 2\mathbf{j} + \mathbf{A}$$

$$\Rightarrow 2\mathbf{i} - 3\mathbf{j} = \mathbf{A}$$

$$\Rightarrow \mathbf{r} = 2e^{-t}\mathbf{j} + (2\mathbf{i} - 3\mathbf{j})e^{-3t}$$

$$= 2e^{-3t}\mathbf{i} + (2e^{-t} - 3e^{-3t})\mathbf{j}$$

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Exercise A, Question 10

Question:

The position vector of a particle P at time t seconds is \mathbf{r} metres. The motion of P is modelled by the vector differential equation

$$\frac{d\mathbf{r}}{dt} - \frac{2}{t}\mathbf{r} = 4\mathbf{j}, t > 0.$$

Given that when $t = 1, \mathbf{r} = \mathbf{i} - \mathbf{j}$, find \mathbf{r} in terms of t .

Solution:

$$\frac{d\mathbf{r}}{dt} - \frac{2}{t}\mathbf{r} = 4\mathbf{j}$$

$$\text{I.F. } e^{\int \frac{-2}{t} dt} = e^{-2 \ln t} = e^{\ln t^{-2}} = \frac{1}{t^2}$$

$$\frac{d}{dt} \left(\mathbf{r} \times \frac{1}{t^2} \right) = \frac{4}{t^2} \mathbf{j}$$

$$\frac{1}{t^2} \mathbf{r} = \int 4t^{-2} \mathbf{j} \, dt$$

$$= \frac{-4}{t} \mathbf{j} + \mathbf{c}$$

$$t = 1, \mathbf{r} = \mathbf{i} - \mathbf{j} \Rightarrow \mathbf{i} - \mathbf{j} = -4\mathbf{j} + \mathbf{c}$$

$$\mathbf{c} = \mathbf{i} + 3\mathbf{j}$$

$$\text{So } \mathbf{r} = (\mathbf{i} + 3\mathbf{j})t^2 - 4t\mathbf{j}$$

$$\text{i.e. } \Rightarrow \mathbf{r} = t^2\mathbf{i} + (3t^2 - 4t)\mathbf{j}$$

$$\text{Check } \frac{d\mathbf{r}}{dt} = 2t\mathbf{i} + (6t - 4)\mathbf{j}$$

$$\text{LHS} = 2t\mathbf{i} + (6t - 4)\mathbf{j} - \frac{2}{t} \{ t^2\mathbf{i} + (3t^2 - 4t)\mathbf{j} \}$$

$$= 4\mathbf{j} = \text{RHS}$$

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Exercise B, Question 1

Question:

At time t seconds the position vector \mathbf{r} metres of a particle P satisfies the vector differential equation

$$\frac{d^2\mathbf{r}}{dt^2} + 4\frac{d\mathbf{r}}{dt} + 8\mathbf{r} = \mathbf{0}.$$

At $t = 0$, $\mathbf{r} = \mathbf{i} + \mathbf{j}$ and the velocity of P is $(2\mathbf{i} - 4\mathbf{j})\text{m s}^{-1}$.

Find an expression for \mathbf{r} in terms of t .

Solution:

$$\frac{d^2\mathbf{r}}{dt^2} + 4\frac{d\mathbf{r}}{dt} + 8\mathbf{r} = \mathbf{0} \Rightarrow \lambda^2 + 4\lambda + 8 = 0$$

$$\Rightarrow (\lambda + 2)^2 = -4$$

$$\Rightarrow \lambda = -2 \pm 2i$$

General solution is $\mathbf{r} = e^{-2t}(\mathbf{A} \cos 2t + \mathbf{B} \sin 2t)$

$$t = 0, \mathbf{r} = \mathbf{i} + \mathbf{j} \Rightarrow \mathbf{i} + \mathbf{j} = \mathbf{A}$$

$$\frac{d\mathbf{r}}{dt} = e^{-2t}(-2\mathbf{A} \sin 2t + 2\mathbf{B} \cos 2t) - 2e^{-2t}(\mathbf{A} \cos 2t + \mathbf{B} \sin 2t)$$

$$t = 0, \mathbf{v} = 2\mathbf{i} - 4\mathbf{j} \Rightarrow 2\mathbf{i} - 4\mathbf{j} = 2\mathbf{B} - 2\mathbf{A}$$

$$\Rightarrow \mathbf{B} = \mathbf{i} - 2\mathbf{j} + \mathbf{i} + \mathbf{j} = 2\mathbf{i} - \mathbf{j}$$

$$\text{So, } \mathbf{r} = e^{-2t}[(\mathbf{i} + \mathbf{j}) \cos 2t + (2\mathbf{i} - \mathbf{j}) \sin 2t]$$

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Exercise B, Question 2

Question:

The position vector \mathbf{r} metres of a particle P at time t seconds satisfies the vector differential equation

$$\frac{d^2\mathbf{r}}{dt^2} + 3\frac{d\mathbf{r}}{dt} + 2\mathbf{r} = \mathbf{0}.$$

At $t = 0$, the particle is at the point with position vector $2\mathbf{j}$ m moving with velocity $(\mathbf{i} + \mathbf{j})\text{ m s}^{-1}$.

Find \mathbf{r} in terms of t .

Solution:

$$\begin{aligned}\frac{d^2\mathbf{r}}{dt^2} + 3\frac{d\mathbf{r}}{dt} + 2\mathbf{r} &= \mathbf{0} \Rightarrow \lambda^2 + 3\lambda + 2 = 0 \\ &\Rightarrow (\lambda + 2)(\lambda + 1) = 0 \\ &\Rightarrow \lambda = -2 \text{ or } -1\end{aligned}$$

General solution is

$$\mathbf{r} = \mathbf{A}e^{-2t} + \mathbf{B}e^{-t}$$

$$t = 0, \mathbf{r} = 2\mathbf{j} \Rightarrow 2\mathbf{j} = \mathbf{A} + \mathbf{B} \quad \text{①}$$

$$\frac{d\mathbf{r}}{dt} = -2\mathbf{A}e^{-2t} - \mathbf{B}e^{-t}$$

$$t = 0, \mathbf{v} = \mathbf{i} + \mathbf{j} \Rightarrow \mathbf{i} + \mathbf{j} = -2\mathbf{A} - \mathbf{B} \quad \text{②}$$

$$\begin{aligned}\text{①} + \text{②}: \quad \mathbf{i} + 3\mathbf{j} &= -\mathbf{A} \Rightarrow \mathbf{A} = -\mathbf{i} - 3\mathbf{j} \\ &\Rightarrow \mathbf{B} = \mathbf{i} + 5\mathbf{j}\end{aligned}$$

$$\text{So, } \mathbf{r} = (-\mathbf{i} - 3\mathbf{j})e^{-2t} + (\mathbf{i} + 5\mathbf{j})e^{-t}$$

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Exercise B, Question 3

Question:

The position vector of a particle P at time t seconds is \mathbf{r} metres. The motion of P is modelled by the differential equation

$$\frac{d^2\mathbf{r}}{dt^2} - 2\frac{d\mathbf{r}}{dt} + \mathbf{r} = \mathbf{0}.$$

Given that when $t = 0$, $\mathbf{r} = \mathbf{i}$ and $\frac{d\mathbf{r}}{dt} = \mathbf{j}$, find the distance of P from the origin O when $t = 2$.

Solution:

$$\begin{aligned}\frac{d^2\mathbf{r}}{dt^2} - 2\frac{d\mathbf{r}}{dt} + \mathbf{r} = \mathbf{0} &\Rightarrow \lambda^2 - 2\lambda + 1 = 0 \\ &\Rightarrow (\lambda - 1)^2 = 0 \\ &\Rightarrow \lambda = 1(\text{twice})\end{aligned}$$

General solution is $\mathbf{r} = e^t(\mathbf{A} + \mathbf{B}t)$

$$t = 0, \mathbf{r} = \mathbf{i} \Rightarrow \mathbf{i} = \mathbf{A}$$

$$\frac{d\mathbf{r}}{dt} = e^t\mathbf{B} + e^t(\mathbf{A} + \mathbf{B}t)$$

$$t = 0, \mathbf{v} = \mathbf{j} \Rightarrow \mathbf{j} = \mathbf{B} + \mathbf{A} \Rightarrow \mathbf{B} = -\mathbf{i} + \mathbf{j}$$

$$\mathbf{r} = e^t[\mathbf{i} + t(-\mathbf{i} + \mathbf{j})]$$

$$\text{When } t = 2, \mathbf{r} = e^2(\mathbf{i} - 2\mathbf{i} + 2\mathbf{j})$$

$$= e^2(-\mathbf{i} + 2\mathbf{j})$$

$$|\mathbf{r}| = e^2\sqrt{(-1)^2 + 2^2} = e^2\sqrt{5} \text{ m}$$

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Exercise B, Question 4

Question:

The position vector of a particle P at time t seconds is \mathbf{r} metres and satisfies the differential equation

$$\frac{d^2\mathbf{r}}{dt^2} + \frac{d\mathbf{r}}{dt} + \mathbf{r} = \mathbf{0}.$$

Given that when $t = 0$, $\mathbf{r} = -2\mathbf{i}$ and $\frac{d\mathbf{r}}{dt} = \mathbf{i} + \sqrt{3}\mathbf{j}$, find \mathbf{r} in terms of t .

Solution:

$$\frac{d^2\mathbf{r}}{dt^2} + \frac{d\mathbf{r}}{dt} + \mathbf{r} = \mathbf{0} \Rightarrow \lambda^2 + \lambda + 1 = 0$$

$$\Rightarrow \left(\lambda + \frac{1}{2}\right)^2 = -\frac{3}{4}$$

$$\Rightarrow \lambda = \frac{-1 \pm i\sqrt{3}}{2}$$

$$\text{General solution is } \mathbf{r} = e^{-\frac{1}{2}t} \left(\mathbf{A} \cos \frac{\sqrt{3}}{2}t + \mathbf{B} \sin \frac{\sqrt{3}}{2}t \right)$$

$$t = 0, \mathbf{r} = -2\mathbf{i} \Rightarrow -2\mathbf{i} = \mathbf{A}$$

$$\frac{d\mathbf{r}}{dt} = e^{-\frac{1}{2}t} \left(-\frac{\sqrt{3}}{2} \mathbf{A} \sin \frac{\sqrt{3}}{2}t + \frac{\sqrt{3}}{2} \mathbf{B} \cos \frac{\sqrt{3}}{2}t \right) - \frac{1}{2} e^{-\frac{1}{2}t} \left(\mathbf{A} \cos \frac{\sqrt{3}}{2}t + \mathbf{B} \sin \frac{\sqrt{3}}{2}t \right)$$

$$t = 0, \mathbf{v} = \mathbf{i} + \sqrt{3}\mathbf{j} \Rightarrow \mathbf{i} + \sqrt{3}\mathbf{j} = \frac{\sqrt{3}}{2} \mathbf{B} - \frac{1}{2} \mathbf{A}$$

$$\Rightarrow \mathbf{i} + \sqrt{3}\mathbf{j} = \frac{\sqrt{3}}{2} \mathbf{B} + \mathbf{i} \Rightarrow \mathbf{B} = 2\mathbf{j}$$

$$\text{So, } \mathbf{r} = e^{-\frac{1}{2}t} \left(-2 \cos \frac{\sqrt{3}}{2}t \mathbf{i} + 2 \sin \frac{\sqrt{3}}{2}t \mathbf{j} \right)$$

Solutionbank M5

Edexcel AS and A Level Modular Mathematics

Exercise B, Question 5

Question:

The position vector of a particle P at time t seconds is \mathbf{r} metres. The motion of P is modelled by the differential equation

$$\frac{d^2\mathbf{r}}{dt^2} + 2\frac{d\mathbf{r}}{dt} = \mathbf{0}.$$

Given that when $t = 0$, $\mathbf{r} = \mathbf{0}$ and $\frac{d\mathbf{r}}{dt} = 4\mathbf{i}$, find \mathbf{r} in terms of t .

Solution:

$$\frac{d^2\mathbf{r}}{dt^2} + 2\frac{d\mathbf{r}}{dt} = \mathbf{0} \Rightarrow \lambda^2 + 2\lambda = 0$$

$$\Rightarrow \lambda(\lambda + 2) = 0$$

$$\Rightarrow \lambda = 0 \text{ or } -2$$

General Solution is $\mathbf{r} = \mathbf{A} + \mathbf{B}e^{-2t}$

$$t = 0, \mathbf{r} = \mathbf{0} \Rightarrow \mathbf{0} = \mathbf{A} + \mathbf{B} \quad \text{①}$$

$$\frac{d\mathbf{r}}{dt} = -2\mathbf{B}e^{-2t}$$

$$t = 0, \frac{d\mathbf{r}}{dt} = 4\mathbf{i} \Rightarrow 4\mathbf{i} = -2\mathbf{B} \Rightarrow \mathbf{B} = -2\mathbf{i}$$

$$\Rightarrow \mathbf{A} = 2\mathbf{i}$$

$$\text{So, } \mathbf{r} = 2\mathbf{i} - 2\mathbf{i}e^{-2t}$$

Solutionbank M5

Edexcel AS and A Level Modular Mathematics

Exercise B, Question 6

Question:

The position vector of a particle P at time t seconds is \mathbf{r} metres and satisfies the differential equation

$$\frac{d^2\mathbf{r}}{dt^2} + \mathbf{r} = 10e^{2t}\mathbf{i}$$

Given that when $t = 0, \mathbf{r} = \mathbf{i}$ and $\frac{d\mathbf{r}}{dt} = 2\mathbf{j}$, find \mathbf{r} in terms of t .

Solution:

$$\frac{d^2\mathbf{r}}{dt^2} + \mathbf{r} = \mathbf{0} \Rightarrow \lambda^2 + 1 = 0 \Rightarrow \lambda = \pm i$$

$$\Rightarrow \text{C.F. is } \mathbf{r} = \mathbf{A} \cos t + \mathbf{B} \sin t$$

For P.I. try $\mathbf{r} = \mathbf{C}e^{2t}$

$$\Rightarrow \frac{d\mathbf{r}}{dt} = 2\mathbf{C}e^{2t} \Rightarrow \frac{d^2\mathbf{r}}{dt^2} = 4\mathbf{C}e^{2t}$$

$$\text{So } 4\mathbf{C}e^{2t} + \mathbf{C}e^{2t} = 10e^{2t}\mathbf{i}$$

$$\Rightarrow \mathbf{C} = 2\mathbf{i}$$

$$\text{P.I. is } \mathbf{r} = 2\mathbf{i}e^{2t}$$

$$\therefore \text{ general solution is } \mathbf{r} = \mathbf{A} \cos t + \mathbf{B} \sin t + 2\mathbf{i}e^{2t}$$

$$t = 0, \mathbf{r} = \mathbf{i} \Rightarrow \mathbf{i} = \mathbf{A} + \mathbf{0} + 2\mathbf{i} \Rightarrow \mathbf{A} = -\mathbf{i}$$

$$\frac{d\mathbf{r}}{dt} = -\mathbf{A} \sin t + \mathbf{B} \cos t + 4e^{2t}\mathbf{i}$$

$$t = 0, \frac{d\mathbf{r}}{dt} = 2\mathbf{j} \Rightarrow 2\mathbf{j} = \mathbf{B} + 4\mathbf{i} \Rightarrow \mathbf{B} = -4\mathbf{i} + 2\mathbf{j}$$

$$\text{So } \mathbf{r} = -\cos t \mathbf{i} + \sin t (-4\mathbf{i} + 2\mathbf{j}) + 2e^{2t}\mathbf{i}$$

$$\text{i.e. } \mathbf{r} = (2e^{2t} - \cos t - 4\sin t)\mathbf{i} + 2\sin t \mathbf{j}$$

Solutionbank M5

Edexcel AS and A Level Modular Mathematics

Exercise B, Question 7

Question:

The position vector of a particle P at time t seconds is \mathbf{r} metres. The motion of P is modelled by the differential equation

$$\frac{d^2\mathbf{r}}{dt^2} - 2\frac{d\mathbf{r}}{dt} + 5\mathbf{r} = 10\sin t\mathbf{i}.$$

Given that when $t = 0$, $\mathbf{r} = 2\mathbf{i} - \mathbf{j}$ and $\frac{d\mathbf{r}}{dt} = \mathbf{i} + \mathbf{j}$, find \mathbf{r} in terms of t .

Solution:

$$\frac{d^2\mathbf{r}}{dt^2} - 2\frac{d\mathbf{r}}{dt} + 5\mathbf{r} = \mathbf{0} \Rightarrow \lambda^2 - 2\lambda + 5 = 0$$

$$\Rightarrow (\lambda - 1)^2 = -4$$

$$\Rightarrow \lambda = 1 \pm 2i$$

$$\Rightarrow \text{C.F. is } \mathbf{r} = e^t(\mathbf{A} \cos 2t + \mathbf{B} \sin 2t)$$

For P.I. try

$$\mathbf{r} = \mathbf{p} \sin t + \mathbf{q} \cos t$$

$$\Rightarrow \dot{\mathbf{r}} = \mathbf{p} \cos t - \mathbf{q} \sin t$$

$$\Rightarrow \ddot{\mathbf{r}} = -\mathbf{p} \sin t - \mathbf{q} \cos t$$

$$\text{So, } -\mathbf{p} \sin t - \mathbf{q} \cos t - 2(\mathbf{p} \cos t - \mathbf{q} \sin t) + 5(\mathbf{p} \sin t + \mathbf{q} \cos t) = 10 \sin t \mathbf{i}$$

$$4\mathbf{p} \sin t + 2\mathbf{q} \sin t + 4\mathbf{q} \cos t - 2\mathbf{p} \cos t = 10 \sin t \mathbf{i}$$

$$4\mathbf{p} + 2\mathbf{q} = 10\mathbf{i} \quad \text{and} \quad 4\mathbf{q} - 2\mathbf{p} = \mathbf{0} \Rightarrow \mathbf{p} = 2\mathbf{q}$$

$$10\mathbf{q} = 10\mathbf{i}$$

$$\mathbf{q} = \mathbf{i} \Rightarrow \mathbf{p} = 2\mathbf{i}$$

$$\text{So P.I. is } \mathbf{r} = 2\mathbf{i} \sin t + \mathbf{i} \cos t$$

General solution is

$$\mathbf{r} = e^t(\mathbf{A} \cos 2t + \mathbf{B} \sin 2t) + 2\mathbf{i} \sin t + \mathbf{i} \cos t$$

$$t = 0, \mathbf{r} = 2\mathbf{i} - \mathbf{j} \Rightarrow 2\mathbf{i} - \mathbf{j} = \mathbf{A} + \mathbf{i} \Rightarrow \mathbf{A} = \mathbf{i} - \mathbf{j}$$

$$\frac{d\mathbf{r}}{dt} = e^t(\mathbf{A} \cos 2t + \mathbf{B} \sin 2t) + e^t(-2\mathbf{A} \sin 2t + 2\mathbf{B} \cos 2t) + 2\mathbf{i} \cos t - \mathbf{i} \sin t$$

$$t = 0, \frac{d\mathbf{r}}{dt} = \mathbf{i} + \mathbf{j} \Rightarrow \mathbf{i} + \mathbf{j} = \mathbf{A} + 2\mathbf{B} + 2\mathbf{i}$$

$$\text{So } \mathbf{i} + \mathbf{j} = \mathbf{i} - \mathbf{j} + 2\mathbf{B} + 2\mathbf{i}$$

$$\mathbf{j} - \mathbf{i} = \mathbf{B}$$

$$\text{So } \mathbf{r} = e^t[(\mathbf{i} - \mathbf{j}) \cos 2t + (-\mathbf{i} + \mathbf{j}) \sin 2t] + 2\mathbf{i} \sin t + \mathbf{i} \cos t$$

$$\text{i.e. } \mathbf{r} = \mathbf{i}(e^t \cos 2t - e^t \sin 2t + 2 \sin t + \cos t) + \mathbf{j}(e^t \sin 2t - e^t \cos 2t)$$

Solutionbank M5

Edexcel AS and A Level Modular Mathematics

Exercise B, Question 8

Question:

The position vector of a particle P at time t seconds is \mathbf{r} metres and satisfies the differential equation

$$\frac{d^2\mathbf{r}}{dt^2} - 4\frac{d\mathbf{r}}{dt} + 4\mathbf{r} = 8\mathbf{i}.$$

At $t = 0$, the particle is at the point with position vector $(2\mathbf{i} - \mathbf{k})\text{m}$ moving with velocity $(\mathbf{i} + 2\mathbf{j})\text{ m s}^{-1}$.

Find \mathbf{r} in terms of t .

Solution:

$$\frac{d^2\mathbf{r}}{dt^2} - 4\frac{d\mathbf{r}}{dt} + 4\mathbf{r} = \mathbf{0} \Rightarrow \lambda^2 - 4\lambda + 4 = 0$$

$$\Rightarrow (\lambda - 2)^2 = 0$$

$$\Rightarrow \lambda = 2 \text{ (twice)}$$

$$\Rightarrow \text{C.F. is } \mathbf{r} = e^{2t}(\mathbf{A} + \mathbf{B}t)$$

For P.I. try $\mathbf{r} = \mathbf{C}$

$$\dot{\mathbf{r}} = \mathbf{0}$$

$$\ddot{\mathbf{r}} = \mathbf{0}$$

$$\text{So } 4\mathbf{C} = 8\mathbf{i} \Rightarrow \mathbf{C} = 2\mathbf{i}$$

$$\text{G.S. is } \mathbf{r} = e^{2t}(\mathbf{A} + \mathbf{B}t) + 2\mathbf{i}$$

$$t = 0, \mathbf{r} = 2\mathbf{i} - \mathbf{k} \Rightarrow 2\mathbf{i} - \mathbf{k} = \mathbf{A} + 2\mathbf{i} \Rightarrow \mathbf{A} = -\mathbf{k}$$

$$\frac{d\mathbf{r}}{dt} = e^{2t}\mathbf{B} + 2e^{2t}(\mathbf{A} + \mathbf{B}t)$$

$$t = 0, \frac{d\mathbf{r}}{dt} = \mathbf{i} + 2\mathbf{j} \Rightarrow \mathbf{i} + 2\mathbf{j} = \mathbf{B} + 2\mathbf{A} \Rightarrow \mathbf{B} = \mathbf{i} + 2\mathbf{j} + 2\mathbf{k}$$

$$\text{So } \mathbf{r} = e^{2t}[-\mathbf{k} + t(\mathbf{i} + 2\mathbf{j} + 2\mathbf{k})] + 2\mathbf{i}$$

Solutionbank M5

Edexcel AS and A Level Modular Mathematics

Exercise B, Question 9

Question:

The position vector of a particle P at time t seconds is \mathbf{r} metres and satisfies the differential equation

$$\frac{d^2\mathbf{r}}{dt^2} - 4\mathbf{r} = 12t\mathbf{i} - 2\mathbf{j}.$$

At $t = 0$, the particle is at the point with position vector $(\mathbf{i} + \mathbf{k})\text{m}$ moving with velocity $2\mathbf{j} \text{ m s}^{-1}$.

Find \mathbf{r} in terms of t .

Solution:

$$\frac{d^2 \mathbf{r}}{dt^2} - 4\mathbf{r} = \mathbf{0} \Rightarrow \lambda^2 - 4 = 0 \Rightarrow \lambda = \pm 2$$

$$\Rightarrow \text{C.F. is } \mathbf{r} = \mathbf{A}e^{2t} + \mathbf{B}e^{-2t}$$

$$\text{For P.I. try } \mathbf{r} = \mathbf{C}t + \mathbf{D}$$

$$\dot{\mathbf{r}} = \mathbf{C}$$

$$\ddot{\mathbf{r}} = \mathbf{0}$$

$$\text{So } \mathbf{0} - 4(\mathbf{C}t + \mathbf{D}) = 12\mathbf{i} - 2\mathbf{j}$$

$$\Rightarrow -4\mathbf{C} = 12\mathbf{i} \Rightarrow \mathbf{C} = -3\mathbf{i}$$

$$-4\mathbf{D} = -2\mathbf{j} \Rightarrow \mathbf{D} = \frac{1}{2}\mathbf{j}$$

$$\text{So P.I. is } \mathbf{r} = -3\mathbf{i}t + \frac{1}{2}\mathbf{j}$$

$$\therefore \text{G.S. is } \mathbf{r} = \mathbf{A}e^{2t} + \mathbf{B}e^{-2t} - 3\mathbf{i}t + \frac{1}{2}\mathbf{j}$$

$$t = 0, \mathbf{r} = \mathbf{i} + \mathbf{k} \Rightarrow \mathbf{i} + \mathbf{k} = \mathbf{A} + \mathbf{B} + \frac{1}{2}\mathbf{j}$$

$$\Rightarrow \mathbf{i} - \frac{1}{2}\mathbf{j} + \mathbf{k} = \mathbf{A} + \mathbf{B} \quad \text{①}$$

$$\frac{d\mathbf{r}}{dt} = 2\mathbf{A}e^{2t} - 2\mathbf{B}e^{-2t} - 3\mathbf{i}$$

$$t = 0, \frac{d\mathbf{r}}{dt} = 2\mathbf{j} \Rightarrow 2\mathbf{j} = 2\mathbf{A} - 2\mathbf{B} - 3\mathbf{i}$$

$$\Rightarrow 3\mathbf{i} + 2\mathbf{j} = 2\mathbf{A} - 2\mathbf{B} \quad \text{②}$$

$$2\mathbf{i} - \mathbf{j} + 2\mathbf{k} = 2\mathbf{A} + 2\mathbf{B} \quad \text{③}$$

Add,

$$5\mathbf{i} + \mathbf{j} + 2\mathbf{k} = 4\mathbf{A}$$

$$\frac{5}{4}\mathbf{i} + \frac{1}{4}\mathbf{j} + \frac{1}{2}\mathbf{k} = \mathbf{A}$$

$$\Rightarrow \frac{-1}{4}\mathbf{i} - \frac{3}{4}\mathbf{j} + \frac{1}{2}\mathbf{k} = \mathbf{B}$$

$$\text{So, } \mathbf{r} = \begin{pmatrix} \frac{5}{4} \\ \frac{1}{4} \\ \frac{1}{2} \end{pmatrix} e^{2t} + \begin{pmatrix} -\frac{1}{4} \\ -\frac{3}{4} \\ \frac{1}{2} \end{pmatrix} e^{-2t} + \begin{pmatrix} -3t \\ \frac{1}{2} \\ 0 \end{pmatrix}$$

Solutionbank M5

Edexcel AS and A Level Modular Mathematics

Exercise B, Question 10

Question:

The position vector of a particle P at time t seconds is \mathbf{r} metres. The motion of P is modelled by the differential equation

$$\frac{d^2\mathbf{r}}{dt^2} - 2\frac{d\mathbf{r}}{dt} - 8\mathbf{r} = (9\mathbf{i} + 18\mathbf{j})e^t.$$

Given that when $t = 0$, $\mathbf{r} = \mathbf{i} + 2\mathbf{j}$ and $\frac{d\mathbf{r}}{dt} = 2\mathbf{i} + \mathbf{j}$, find \mathbf{r} in terms of t .

Solution:

$$\frac{d^2\mathbf{r}}{dt^2} - 2\frac{d\mathbf{r}}{dt} - 8\mathbf{r} = \mathbf{0} \Rightarrow \lambda^2 - 2\lambda - 8 = 0$$

$$\Rightarrow (\lambda - 4)(\lambda + 2) = 0$$

$$\Rightarrow \lambda = 4 \text{ or } -2$$

$$\Rightarrow \text{C.F. is } \mathbf{r} = \mathbf{A}e^{4t} + e^{-2t}\mathbf{B}$$

For P.I. try

$$\mathbf{r} = \mathbf{C}e^t$$

$$\dot{\mathbf{r}} = \mathbf{C}e^t$$

$$\ddot{\mathbf{r}} = \mathbf{C}e^t$$

$$\mathbf{C}e^t - 2\mathbf{C}e^t - 8\mathbf{C}e^t = (9\mathbf{i} + 18\mathbf{j})e^t$$

$$-9\mathbf{C} = 9\mathbf{i} + 18\mathbf{j} \Rightarrow \mathbf{C} = -\mathbf{i} - 2\mathbf{j}$$

$$\text{So P.I. is } \mathbf{r} = (-\mathbf{i} - 2\mathbf{j})e^t$$

$$\therefore \text{G.S. is } \mathbf{r} = \mathbf{A}e^{4t} + \mathbf{B}e^{-2t} + (-\mathbf{i} - 2\mathbf{j})e^t$$

$$t = 0, \mathbf{r} = \mathbf{i} + 2\mathbf{j} \Rightarrow \mathbf{i} + 2\mathbf{j} = \mathbf{A} + \mathbf{B} + (-\mathbf{i} - 2\mathbf{j})$$

$$\Rightarrow 2\mathbf{i} + 4\mathbf{j} = \mathbf{A} + \mathbf{B} \quad \text{①}$$

$$\frac{d\mathbf{r}}{dt} = 4\mathbf{A}e^{4t} - 2\mathbf{B}e^{-2t} + (-\mathbf{i} - 2\mathbf{j})e^t$$

$$t = 0, \frac{d\mathbf{r}}{dt} = 2\mathbf{i} + \mathbf{j} \Rightarrow 2\mathbf{i} + \mathbf{j} = 4\mathbf{A} - 2\mathbf{B} - \mathbf{i} - 2\mathbf{j}$$

$$\Rightarrow 3\mathbf{i} + 3\mathbf{j} = 4\mathbf{A} - 2\mathbf{B} \quad \text{②}$$

$$2\mathbf{i} + 4\mathbf{j} = \mathbf{A} + \mathbf{B} \quad \text{①}$$

$$3\mathbf{i} + 3\mathbf{j} = 4\mathbf{A} - 2\mathbf{B} \quad \text{②}$$

$$4\mathbf{i} + 8\mathbf{j} = 2\mathbf{A} + 2\mathbf{B} \quad \text{②} \times \text{①}$$

$$7\mathbf{i} + 11\mathbf{j} = 6\mathbf{A}$$

$$\frac{7}{6}\mathbf{i} + \frac{11}{6}\mathbf{j} = \mathbf{A} \Rightarrow \mathbf{B} = \frac{5}{6}\mathbf{i} + \frac{13}{6}\mathbf{j}$$

$$\mathbf{r} = \left(\frac{7}{6}\mathbf{i} + \frac{11}{6}\mathbf{j}\right)e^{4t} + \left(\frac{5}{6}\mathbf{i} + \frac{13}{6}\mathbf{j}\right)e^{-2t} + (-\mathbf{i} - 2\mathbf{j})e^t$$

Solutionbank M5

Edexcel AS and A Level Modular Mathematics

Exercise C, Question 1

Question:

In each of the following cases calculate the work done by the force \mathbf{F} as it moves its point of application through the displacement \mathbf{d} :

a $\mathbf{F} = (3\mathbf{i} + \mathbf{j} - 2\mathbf{k})\text{N}$, $\mathbf{d} = (\mathbf{i} + \mathbf{j} - 2\mathbf{k})\text{m}$.

b $\mathbf{F} = (-4\mathbf{i} - \mathbf{j} + 2\mathbf{k})\text{N}$, $\mathbf{d} = (3\mathbf{i} - \mathbf{j} + 4\mathbf{k})\text{m}$.

c $\mathbf{F} = (\mathbf{i} - 2\mathbf{k})\text{N}$, $\mathbf{d} = (\mathbf{j} - 3\mathbf{k})\text{m}$.

Solution:

$$\mathbf{a} \quad \begin{pmatrix} 3 \\ 1 \\ -2 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} = 3 + 1 + 4 = 8 \text{ J}$$

$$\mathbf{b} \quad \begin{pmatrix} -4 \\ -1 \\ 2 \end{pmatrix} \cdot \begin{pmatrix} 3 \\ -1 \\ 4 \end{pmatrix} = -12 + 1 + 8 = -3 \text{ J}$$

$$\mathbf{c} \quad \begin{pmatrix} 1 \\ 0 \\ -2 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 1 \\ -3 \end{pmatrix} = 6 \text{ J}$$

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Exercise C, Question 2

Question:

In each of the following cases calculate the work done by the force \mathbf{F} as it moves its point of application from the point A with position vector \mathbf{r}_A to the point B with position vector \mathbf{r}_B :

- a** $\mathbf{F} = (\mathbf{i} + \mathbf{j} - 2\mathbf{k})\text{N}$, $\mathbf{r}_A = (\mathbf{i} + \mathbf{j} - 2\mathbf{k})\text{m}$, $\mathbf{r}_B = (2\mathbf{i} - 3\mathbf{j} + \mathbf{k})\text{m}$.
b $\mathbf{F} = (2\mathbf{i} - \mathbf{j} + 3\mathbf{k})\text{N}$, $\mathbf{r}_A = (2\mathbf{i} - \mathbf{j} + \mathbf{k})\text{m}$, $\mathbf{r}_B = (4\mathbf{i} - 3\mathbf{j} - 2\mathbf{k})\text{m}$.
c $\mathbf{F} = (\mathbf{i} - \mathbf{k})\text{N}$, $\mathbf{r}_A = (2\mathbf{i} - \mathbf{j})\text{m}$, $\mathbf{r}_B = (3\mathbf{i} - \mathbf{j} + \mathbf{k})\text{m}$.

Solution:

$$\mathbf{a} \quad \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ -4 \\ 3 \end{pmatrix} = 1 - 4 - 6 = -9 \text{ J}$$

$$\mathbf{b} \quad \begin{pmatrix} 2 \\ -1 \\ 3 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ -2 \\ -3 \end{pmatrix} = 4 + 2 - 9 = -3 \text{ J}$$

$$\mathbf{c} \quad \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = 1 + 0 - 1 = 0 \text{ J}$$

Solutionbank M5

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Exercise C, Question 3

Question:

In each of the following cases a particle P of mass 0.5 kg is moved from the point A with position vector \mathbf{r}_A to the point B with position vector \mathbf{r}_B by a force \mathbf{F} . Assuming that in each case there are no other forces, apart from \mathbf{F} , doing work on P and that the speed of P at the point A is 4 m s^{-1} , find in each case the speed of P when it reaches the point B :

- a $\mathbf{F} = (\mathbf{i} - \mathbf{j} + 2\mathbf{k})\text{N}$, $\mathbf{r}_A = (\mathbf{i} + \mathbf{j} - 2\mathbf{k}) \text{ m}$, $\mathbf{r}_B = (2\mathbf{i} - 3\mathbf{j} + \mathbf{k}) \text{ m}$.
 b $\mathbf{F} = (2\mathbf{i} - \mathbf{j} - 3\mathbf{k})\text{N}$, $\mathbf{r}_A = (2\mathbf{i} - \mathbf{j} + \mathbf{k}) \text{ m}$, $\mathbf{r}_B = (4\mathbf{i} - 3\mathbf{j} - 2\mathbf{k}) \text{ m}$.
 c $\mathbf{F} = (\mathbf{i} - \mathbf{k})\text{N}$, $\mathbf{r}_A = (2\mathbf{i} - \mathbf{j}) \text{ m}$, $\mathbf{r}_B = (3\mathbf{i} - \mathbf{j} + \mathbf{k}) \text{ m}$.

Solution:

- a work done = K.E. gain

$$\begin{pmatrix} 1 \\ -1 \\ +2 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ -4 \\ 3 \end{pmatrix} = \frac{1}{2} \times 0.5(v^2 - 4^2)$$

$$1 + 4 + 6 = \frac{1}{4}(v^2 - 16)$$

$$60 = v^2$$

$$\sqrt{60} \text{ m s}^{-1} = v$$

b $\begin{pmatrix} 2 \\ -1 \\ -3 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ -2 \\ -3 \end{pmatrix} = \frac{1}{2} \times 0.5(v^2 - 4^2)$

$$4 + 2 + 9 = \frac{1}{4}(v^2 - 16)$$

$$76 = v^2$$

$$\sqrt{76} \text{ m s}^{-1} = v$$

c $\begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = \frac{1}{2} \times 0.5(v^2 - 4^2)$

$$1 + 0 - 1 = \frac{1}{4}(v^2 - 16)$$

$$16 = v^2$$

$$4 \text{ m s}^{-1} = v$$

Solutionbank M5

Edexcel AS and A Level Modular Mathematics

Exercise C, Question 4

Question:

Forces of magnitudes 6 N, 7 N and 9 N act in the directions $2\mathbf{i} + 2\mathbf{j} + \mathbf{k}$, $6\mathbf{i} - 3\mathbf{j} + 2\mathbf{k}$, and $7\mathbf{i} + 4\mathbf{j} - 4\mathbf{k}$, respectively. The three forces act on a particle causing a displacement of $(34\mathbf{i} + 10\mathbf{j})\text{m}$.

- Find the work done by each force.
- Verify that the total work done by all three forces is equal to the work done by the resultant force.

Solution:

$$\mathbf{F}_1 = 6 \times \frac{1}{\sqrt{2^2 + 2^2 + 1^2}} \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 4 \\ 4 \\ 2 \end{pmatrix}$$

$$\mathbf{F}_2 = 7 \times \frac{1}{\sqrt{6^2 + (-3)^2 + 2^2}} \begin{pmatrix} 6 \\ -3 \\ 2 \end{pmatrix} = \begin{pmatrix} 6 \\ -3 \\ 2 \end{pmatrix}$$

$$\mathbf{F}_3 = 9 \times \frac{1}{\sqrt{7^2 + 4^2 + (-4)^2}} \begin{pmatrix} 7 \\ 4 \\ -4 \end{pmatrix} = \begin{pmatrix} 7 \\ 4 \\ -4 \end{pmatrix}$$

$$\mathbf{a} \quad \begin{pmatrix} 4 \\ 4 \\ 2 \end{pmatrix} \cdot \begin{pmatrix} 34 \\ 10 \\ 0 \end{pmatrix} = 136 + 40 = 176 \text{ J}$$

$$\begin{pmatrix} 6 \\ -3 \\ 2 \end{pmatrix} \cdot \begin{pmatrix} 34 \\ 10 \\ 0 \end{pmatrix} = 204 - 30 = 174 \text{ J}$$

$$\begin{pmatrix} 7 \\ 4 \\ -4 \end{pmatrix} \cdot \begin{pmatrix} 34 \\ 10 \\ 0 \end{pmatrix} = 238 + 40 = 278 \text{ J}$$

$$\mathbf{b} \text{ Total work done} = 628 \text{ J}$$

$$\mathbf{p} = \begin{pmatrix} 4 \\ 4 \\ 2 \end{pmatrix} + \begin{pmatrix} 6 \\ -3 \\ 2 \end{pmatrix} + \begin{pmatrix} 7 \\ 4 \\ -4 \end{pmatrix} = \begin{pmatrix} 17 \\ 5 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 17 \\ 5 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 34 \\ 10 \\ 0 \end{pmatrix} = 578 + 50 = 628 \text{ J}$$

Solutionbank M5

Edexcel AS and A Level Modular Mathematics

Exercise C, Question 5

Question:

In each of the following cases the force \mathbf{F} acts through the point with position vector \mathbf{r} relative to the origin O . Find the vector moment of \mathbf{F} about O .

a $\mathbf{F} = (\mathbf{i} + 2\mathbf{j})\text{N}, \mathbf{r} = (\mathbf{i} - \mathbf{j})\text{m}$.

b $\mathbf{F} = (\mathbf{i} + 2\mathbf{k})\text{N}, \mathbf{r} = (2\mathbf{i} - \mathbf{k})\text{m}$.

c $\mathbf{F} = (\mathbf{i} - \mathbf{j})\text{N}, \mathbf{r} = 3\mathbf{k}\text{m}$.

d $\mathbf{F} = (\mathbf{i} + \mathbf{j} - 2\mathbf{k})\text{N}, \mathbf{r} = (3\mathbf{i} - \mathbf{j} + \mathbf{k})\text{m}$.

Solution:

a $\begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} \times \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 3 \end{pmatrix} \text{Nm}$

b $\begin{pmatrix} 2 \\ 0 \\ -1 \end{pmatrix} \times \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} = \begin{pmatrix} 0 \\ -5 \\ 0 \end{pmatrix} \text{Nm}$

c $\begin{pmatrix} 0 \\ 0 \\ 3 \end{pmatrix} \times \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} = \begin{pmatrix} 3 \\ 3 \\ 0 \end{pmatrix} \text{Nm}$

d $\begin{pmatrix} 3 \\ -1 \\ 1 \end{pmatrix} \times \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} = \begin{pmatrix} 1 \\ 7 \\ 4 \end{pmatrix} \text{Nm}$

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Edexcel AS and A Level Modular Mathematics

Exercise C, Question 6

Question:

In each of the following cases the force \mathbf{F} acts through the point with position vector \mathbf{r} relative to the origin O . Find the vector moment of \mathbf{F} about the point A .

a $\mathbf{F} = (\mathbf{i} + \mathbf{j} - \mathbf{k})\text{ N}, \mathbf{r} = (3\mathbf{i} - 2\mathbf{j})\text{ m}, A(0, 1, 0),$

b $\mathbf{F} = (2\mathbf{i} - \mathbf{j})\text{ N}, \mathbf{r} = (\mathbf{i} + 2\mathbf{j})\text{ m}, A(0, 1),$

c $\mathbf{F} = (\mathbf{i} + 2\mathbf{k})\text{ N}, \mathbf{r} = (\mathbf{i} + \mathbf{j} - \mathbf{k})\text{ m}, A(2, 0, 2).$

Solution:

$$\mathbf{a} \quad \begin{pmatrix} 3-0 \\ -2-1 \\ 0-0 \end{pmatrix} \times \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 3 \\ -3 \\ 0 \end{pmatrix} \times \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 3 \\ 3 \\ 6 \end{pmatrix} \text{ Nm}$$

$$\mathbf{b} \quad \begin{pmatrix} 1-0 \\ 2-1 \\ 0-0 \end{pmatrix} \times \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \times \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -3 \end{pmatrix} \text{ Nm}$$

$$\mathbf{c} \quad \begin{pmatrix} 1-2 \\ 1-0 \\ -1-2 \end{pmatrix} \times \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \\ -3 \end{pmatrix} \times \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix} \text{ Nm}$$

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Exercise C, Question 7

Question:

A force \mathbf{F} acts through a point with position vector \mathbf{p} . Find, in terms of \mathbf{F} , \mathbf{p} and \mathbf{q} , the vector moment of \mathbf{F} about the point with position vector \mathbf{q} .

Solution:

$$(\mathbf{p} - \mathbf{q}) \times \mathbf{F} = \mathbf{p} \times \mathbf{F} - \mathbf{q} \times \mathbf{F}$$

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Exercise C, Question 8

Question:

In each of the following cases the force \mathbf{F} has vector moment \mathbf{n} about the origin O .
Find a vector equation of the line of action of \mathbf{F} if

a $\mathbf{F} = (\mathbf{i} + \mathbf{j})\text{N}$, $\mathbf{n} = 4\mathbf{k} \text{ Nm}$,

b $\mathbf{F} = (2\mathbf{i} - \mathbf{j})\text{N}$, $\mathbf{n} = (\mathbf{i} + 2\mathbf{j}) \text{ Nm}$,

c $\mathbf{F} = (\mathbf{i} + \mathbf{j} - \mathbf{k})\text{N}$, $\mathbf{n} = (3\mathbf{i} - 2\mathbf{j} + \mathbf{k}) \text{ Nm}$.

Solution:

$$\mathbf{a} \quad \mathbf{r} \times \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 4 \end{pmatrix} \text{ i.e. } \begin{pmatrix} x \\ y \\ z \end{pmatrix} \times \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 4 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} -z \\ z \\ x-y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 4 \end{pmatrix}$$

$$\Rightarrow z=0, x-y=4$$

Let $y=0, x=4$

$$\text{Equation is } \mathbf{r} = \begin{pmatrix} 4 \\ 0 \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

$$\mathbf{b} \quad \mathbf{r} \times \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix} \text{ i.e. } \begin{pmatrix} x \\ y \\ z \end{pmatrix} \times \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} z \\ 2z \\ -x-2y \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}$$

$$\Rightarrow z=1, -x-2y=0$$

Let $y=0, x=0$

$$\text{equation is } \mathbf{r} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} + \lambda \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix}$$

$$\mathbf{c} \quad \mathbf{r} \times \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 3 \\ -2 \\ 1 \end{pmatrix} \text{ i.e. } \begin{pmatrix} x \\ y \\ z \end{pmatrix} \times \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 3 \\ -2 \\ 1 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} -y-z \\ z+x \\ x-y \end{pmatrix} = \begin{pmatrix} 3 \\ -2 \\ 1 \end{pmatrix}$$

$$\Rightarrow -y-z=3; z+x=-2; x-y=1$$

Let $y=0 \Rightarrow z=-3$ and $x=1$

$$\text{Equation is } \mathbf{r} = \begin{pmatrix} 1 \\ 0 \\ -3 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}$$

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Exercise C, Question 9

Question:

In each of the following cases the force \mathbf{F} acts through a point P . Find a vector equation of the axis through the point Q about which the moment of \mathbf{F} is calculated.

a $\mathbf{F} = (\mathbf{i} - 2\mathbf{j})\text{N}$, $P(0, 1, 0)$, $Q(0, 0, 0)$,

b $\mathbf{F} = (\mathbf{j} + 2\mathbf{k})\text{N}$, $P(\mathbf{i} + \mathbf{k})\text{m}$, $Q(\mathbf{i} + 2\mathbf{j} - \mathbf{k})\text{m}$,

c $\mathbf{F} = (2\mathbf{i} + \mathbf{j} - \mathbf{k})\text{N}$, $P(\mathbf{i} + \mathbf{j} + 2\mathbf{k})\text{m}$, $Q(-\mathbf{i} + 2\mathbf{j} - \mathbf{k})\text{m}$.

Solution:

a
$$\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \times \begin{pmatrix} 1 \\ -2 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix}$$

$$\mathbf{r} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} = \lambda \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} \text{ is equation of axis.}$$

b
$$\begin{pmatrix} 0 \\ -2 \\ 2 \end{pmatrix} \times \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix} = \begin{pmatrix} -6 \\ 0 \\ 0 \end{pmatrix}$$

$$\mathbf{r} = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} + \lambda \begin{pmatrix} -6 \\ 0 \\ 0 \end{pmatrix} \text{ is equation of axis.}$$

c
$$\begin{pmatrix} 2 \\ -1 \\ 3 \end{pmatrix} \times \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} -2 \\ 8 \\ 4 \end{pmatrix}$$

$$\mathbf{r} = \begin{pmatrix} -1 \\ 2 \\ -1 \end{pmatrix} + \lambda \begin{pmatrix} -2 \\ 8 \\ 4 \end{pmatrix} \text{ is equation of axis.}$$

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Exercise C, Question 10

Question:

The moment of a non-zero force \mathbf{F} about a point P is equal to its moment about another point Q . Show that the line of action of \mathbf{F} is parallel to the line PQ .

Solution:

Let \mathbf{T} be the position vector of a point on the line of action of \mathbf{F} .

Let $\overrightarrow{OP} = \mathbf{p}$ and $\overrightarrow{OQ} = \mathbf{q}$

Then the moment of \mathbf{F} about P is $(\mathbf{T} - \mathbf{p}) \times \mathbf{F}$ and about Q is $(\mathbf{T} - \mathbf{q}) \times \mathbf{F}$

Therefore $(\mathbf{T} - \mathbf{p}) \times \mathbf{F} = (\mathbf{T} - \mathbf{q}) \times \mathbf{F} \Rightarrow \mathbf{T} \times \mathbf{F} - \mathbf{p} \times \mathbf{F} = \mathbf{T} \times \mathbf{F} - \mathbf{q} \times \mathbf{F}$

$$\Rightarrow \mathbf{p} \times \mathbf{F} = \mathbf{q} \times \mathbf{F}$$

$$\Rightarrow \mathbf{p} \times \mathbf{F} - \mathbf{q} \times \mathbf{F} = \mathbf{0}$$

$$\Rightarrow (\mathbf{p} - \mathbf{q}) \times \mathbf{F} = \mathbf{0}$$

$$\Rightarrow \overrightarrow{QP} \times \mathbf{F} = \mathbf{0}$$

← Since $\mathbf{F} \neq \mathbf{0}$, \overrightarrow{QP} must be parallel to \mathbf{F}

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Exercise D, Question 1

Question:

Prove that the following system of forces reduces to a couple:

$\mathbf{F}_1 = (\mathbf{i} + 2\mathbf{j} - 3\mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_1 = (\mathbf{i} - \mathbf{j} + 2\mathbf{k})\text{m}$,

$\mathbf{F}_2 = (-3\mathbf{i} + \mathbf{j} - 3\mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_2 = (3\mathbf{i} + \mathbf{k})\text{m}$,

$\mathbf{F}_3 = (\mathbf{i} - \mathbf{j} + 2\mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_3 = (2\mathbf{i} + \mathbf{j} - \mathbf{k})\text{m}$,

$\mathbf{F}_4 = (\mathbf{i} - 2\mathbf{j} + 4\mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_4 = (\mathbf{j} - 2\mathbf{k})\text{m}$.

Solution:

$$\begin{aligned}\sum \mathbf{F}_i &= \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix} + \begin{pmatrix} -3 \\ 1 \\ -3 \end{pmatrix} + \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} + \begin{pmatrix} 1 \\ -2 \\ 4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \\ \sum \mathbf{r}_i \times \mathbf{F}_i &= \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} \times \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix} + \begin{pmatrix} 3 \\ 0 \\ 1 \end{pmatrix} \times \begin{pmatrix} -3 \\ 1 \\ -3 \end{pmatrix} + \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix} \times \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \\ -2 \end{pmatrix} \times \begin{pmatrix} 1 \\ -2 \\ 4 \end{pmatrix} \\ &= \begin{pmatrix} -1 \\ 5 \\ 3 \end{pmatrix} + \begin{pmatrix} -1 \\ 6 \\ 3 \end{pmatrix} + \begin{pmatrix} 1 \\ -5 \\ -3 \end{pmatrix} + \begin{pmatrix} 0 \\ -2 \\ -1 \end{pmatrix} \\ &= \begin{pmatrix} -1 \\ 4 \\ 2 \end{pmatrix} \quad \text{Hence system is a couple of vector moment } (-\mathbf{i} + 4\mathbf{j} + 2\mathbf{k})\text{Nm}.\end{aligned}$$

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Exercise D, Question 2

Question:

Prove that the following system of forces is in equilibrium:

$\mathbf{F}_1 = (\mathbf{i} - \mathbf{j})\text{N}$ acting at the point with position vector $\mathbf{r}_1 = (\mathbf{i} + \mathbf{k})\text{m}$,

$\mathbf{F}_2 = (2\mathbf{j} + \mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_2 = (\mathbf{i} - 2\mathbf{j})\text{m}$,

$\mathbf{F}_3 = (-2\mathbf{i} - \mathbf{j})\text{N}$ acting at the point with position vector $\mathbf{r}_3 = (3\mathbf{i} + \mathbf{j} + \mathbf{k})\text{m}$,

$\mathbf{F}_4 = (\mathbf{i} - \mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_4 = 2\mathbf{i}\text{ m}$.

Solution:

$$\begin{aligned}\sum \mathbf{F}_i &= \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix} + \begin{pmatrix} -2 \\ -1 \\ 0 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \\ \sum \mathbf{r}_i \times \mathbf{F}_i &= \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \times \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} + \begin{pmatrix} 1 \\ -2 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix} + \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix} \times \begin{pmatrix} -2 \\ -1 \\ 0 \end{pmatrix} + \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix} \times \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} \\ &= \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} + \begin{pmatrix} -2 \\ -1 \\ 2 \end{pmatrix} + \begin{pmatrix} 1 \\ -2 \\ -1 \end{pmatrix} + \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad \text{Hence system is in equilibrium.}\end{aligned}$$

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Exercise D, Question 3

Question:

A system consists of three forces $\mathbf{F}_1, \mathbf{F}_2$ and \mathbf{F}_3 . The forces \mathbf{F}_1 and \mathbf{F}_2 act at the points $(2, -1, 0)$ and $(2, 0, 1)$ respectively. $\mathbf{F}_1 = (\mathbf{i} - 2\mathbf{j})\text{N}$; $\mathbf{F}_2 = (\mathbf{j} + \mathbf{k})\text{N}$; \mathbf{F}_3 has magnitude $\sqrt{11}\text{N}$ and acts along the line whose equation is $\mathbf{r} = 5\mathbf{i} - \mathbf{k} + \lambda(3\mathbf{i} + \mathbf{j} - \mathbf{k})$.
Prove that the system reduces to a single force and find a vector equation for its line of action.

Solution:

$$\mathbf{F}_3 = \frac{1}{\sqrt{3^2 + 1^2 + (-1)^2}} \cdot \sqrt{11} \begin{pmatrix} 3 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \\ -1 \end{pmatrix}$$

$$\sum \mathbf{F}_i = \begin{pmatrix} 1 \\ -2 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} + \begin{pmatrix} 3 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 4 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{aligned} \sum \mathbf{r}_i \times \mathbf{F}_i &= \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} \times \begin{pmatrix} 1 \\ -2 \\ 0 \end{pmatrix} + \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix} \times \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} + \begin{pmatrix} 5 \\ 0 \\ -1 \end{pmatrix} \times \begin{pmatrix} 3 \\ 1 \\ -1 \end{pmatrix} \\ &= \begin{pmatrix} 0 \\ 0 \\ -3 \end{pmatrix} + \begin{pmatrix} -1 \\ -2 \\ 2 \end{pmatrix} + \begin{pmatrix} 1 \\ 2 \\ 5 \end{pmatrix} \\ &= \begin{pmatrix} 0 \\ 0 \\ 4 \end{pmatrix} \end{aligned}$$

$$\sum \mathbf{r}_i \times \mathbf{F}_i \cdot \sum \mathbf{F}_i = \begin{pmatrix} 0 \\ 0 \\ 4 \end{pmatrix} \cdot \begin{pmatrix} 4 \\ 0 \\ 0 \end{pmatrix} = 0$$

Hence the resultant is coplanar with the couple

Hence system reduces to a single force.

$$\mathbf{r} \times \begin{pmatrix} 4 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 4 \end{pmatrix} \text{ for a point } \mathbf{r} \text{ on the line of action}$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \times \begin{pmatrix} 4 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 4 \end{pmatrix}$$

$$\begin{pmatrix} 0 \\ 4z \\ -4y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 4 \end{pmatrix} \Rightarrow z = 0, y = -1 \quad x = \lambda \text{ (anything)}$$

$$\therefore \mathbf{r} = \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \text{ is vector equation.}$$

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Exercise D, Question 4

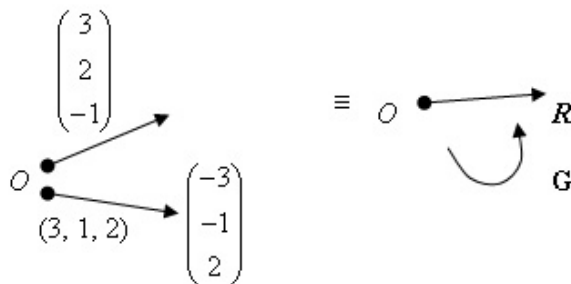
Question:

The line of action of a force $(3\mathbf{i} + 2\mathbf{j} - \mathbf{k})\text{N}$ passes through the origin O and the line of action of a force $(-3\mathbf{i} - \mathbf{j} + 2\mathbf{k})\text{N}$ passes through the point with position vector $(3\mathbf{i} + \mathbf{j} + 2\mathbf{k})\text{m}$.

- Reduce the system of two forces to a single force acting through the origin O together with a couple.
- Find the magnitude of the couple.

Solution:

a



$$\mathbf{R} = \begin{pmatrix} 3 \\ 2 \\ -1 \end{pmatrix} + \begin{pmatrix} -3 \\ -1 \\ 2 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$$

Comparing moments about O ,

$$\begin{pmatrix} 3 \\ 1 \\ 2 \end{pmatrix} \times \begin{pmatrix} -3 \\ -1 \\ 2 \end{pmatrix} = \mathbf{G}$$

$$\begin{pmatrix} 4 \\ -12 \\ 0 \end{pmatrix} = \mathbf{G}$$

Single force is $(\mathbf{j} + \mathbf{k})\text{N}$

Couple has vector moment $(4\mathbf{i} - 12\mathbf{j})\text{Nm}$

$$\text{b } |\mathbf{G}| = \sqrt{4^2 + (-12)^2} = \sqrt{160} = 4\sqrt{10}\text{Nm}$$

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Exercise D, Question 5

Question:

Two forces $4\mathbf{j}$ N and $3\mathbf{k}$ N act through the points with position vectors $(\mathbf{i} + \mathbf{j})$ m and $(\mathbf{j} + \mathbf{k})$ m respectively. A third force acts through the point with position vector $(\mathbf{i} + \mathbf{k})$ m and is such that the three forces are equivalent to a couple. Find the vector moment and the magnitude of this couple.

Solution:

$$4\mathbf{j} + 3\mathbf{k} + \mathbf{F}_3 = \mathbf{0} \quad (\text{since system reduces to a couple})$$

$$\Rightarrow \mathbf{F}_3 = (-4\mathbf{j} - 3\mathbf{k})\text{N}$$

$$\begin{aligned} \mathbf{G} = \sum \mathbf{r}_i \times \mathbf{f}_i &= \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 4 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \times \begin{pmatrix} 0 \\ 0 \\ 3 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \times \begin{pmatrix} 0 \\ -4 \\ -3 \end{pmatrix} \\ &= \begin{pmatrix} 0 \\ 0 \\ 4 \end{pmatrix} + \begin{pmatrix} 3 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 4 \\ 3 \\ -4 \end{pmatrix} \\ &= \begin{pmatrix} 7 \\ 3 \\ 0 \end{pmatrix} \text{ Nm} = (7\mathbf{i} + 3\mathbf{j})\text{Nm} \end{aligned}$$

$$|\mathbf{G}| = \sqrt{7^2 + 3^2} = \sqrt{58} \text{ Nm}$$

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Exercise D, Question 6

Question:

In each of the following cases find the simplest system of forces which is equivalent to the given system:

- a $\mathbf{F}_1 = (-2\mathbf{i} + 3\mathbf{j} + \mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_1 = (-\mathbf{i} + 2\mathbf{j} - \mathbf{k})\text{m}$,
 $\mathbf{F}_2 = (-2\mathbf{j} - \mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_2 = 3\mathbf{j}\text{m}$,
 $\mathbf{F}_3 = (\mathbf{i} - \mathbf{j} + \mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_3 = (\mathbf{i} - 2\mathbf{k})\text{m}$.
- b $\mathbf{F}_1 = (2\mathbf{i} - \mathbf{j})\text{N}$ acting at the point with position vector $\mathbf{r}_1 = (\mathbf{i} + 2\mathbf{j})\text{m}$,
 $\mathbf{F}_2 = (3\mathbf{i} + \mathbf{j})\text{N}$ acting at the point with position vector $\mathbf{r}_2 = (2\mathbf{i} + 3\mathbf{j})\text{m}$,
 $\mathbf{F}_3 = (-\mathbf{i} + \mathbf{j})\text{N}$ acting at the point with position vector $\mathbf{r}_3 = -2\mathbf{j}\text{m}$.
- c Forces \mathbf{PQ} , \mathbf{QR} and \mathbf{RP} where the points P , Q and R have position vectors \mathbf{p} , \mathbf{q} and \mathbf{r} respectively.
- d Forces \mathbf{AB} , \mathbf{BC} , \mathbf{CD} and \mathbf{DA} where the $ABCD$ is a regular tetrahedron.
- e Force $(\mathbf{i} + 3\mathbf{j})\text{N}$ acting at the origin O and a couple of vector moment $3\mathbf{k}\text{Nm}$.

Solution:

$$\begin{aligned}
 \text{a} \quad \sum \mathbf{F}_i &= \begin{pmatrix} -2 \\ 3 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ -2 \\ -1 \end{pmatrix} + \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \\
 \sum \mathbf{r}_i \times \mathbf{F}_i &= \begin{pmatrix} -1 \\ 2 \\ -1 \end{pmatrix} \times \begin{pmatrix} -2 \\ 3 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ 3 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ -2 \\ -1 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \\ -2 \end{pmatrix} \times \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \\
 &= \begin{pmatrix} +5 \\ 3 \\ 1 \end{pmatrix} + \begin{pmatrix} -3 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} -2 \\ -3 \\ -1 \end{pmatrix} \\
 &= \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}
 \end{aligned}$$

Hence system reduces to a single force $(-\mathbf{i} + \mathbf{k})\text{N}$ acting through the origin O .

$$\begin{aligned}
 \text{b} \quad \sum \mathbf{F}_i &= \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} + \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix} + \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 4 \\ 1 \\ 0 \end{pmatrix} \\
 \sum \mathbf{r}_i \times \mathbf{F}_i &= \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix} \times \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} + \begin{pmatrix} 2 \\ 3 \\ 0 \end{pmatrix} \times \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ -2 \\ 0 \end{pmatrix} \times \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \\
 &= \begin{pmatrix} 0 \\ 0 \\ -5 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ -7 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ -2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -14 \end{pmatrix} \\
 \sum \mathbf{F}_i \cdot \sum \mathbf{r}_i \times \mathbf{F}_i &= \begin{pmatrix} 4 \\ 1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 0 \\ -14 \end{pmatrix} = 0
 \end{aligned}$$

Hence resultant force is coplanar with the couple.

Point on line of action given by

$$\begin{aligned}
 \mathbf{r} \times \begin{pmatrix} 4 \\ 1 \\ 0 \end{pmatrix} &= \begin{pmatrix} 0 \\ 0 \\ -14 \end{pmatrix} \text{ i.e. } \begin{pmatrix} x \\ y \\ z \end{pmatrix} \times \begin{pmatrix} 4 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -14 \end{pmatrix} \\
 \Rightarrow \begin{pmatrix} -z \\ 4z \\ x-4y \end{pmatrix} &= \begin{pmatrix} 0 \\ 0 \\ -14 \end{pmatrix} & \Rightarrow \begin{cases} z=0 \\ x-4y=-14 \end{cases}
 \end{aligned}$$

Let $y=0 \Rightarrow x=-14$

Single force $(4\mathbf{i} + \mathbf{j})\text{N}$

$$\therefore \text{Line of action has equation } \mathbf{r} = \begin{pmatrix} -14 \\ 0 \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} 4 \\ 1 \\ 0 \end{pmatrix}$$

$$\text{c } \sum \mathbf{F}_i = \overrightarrow{PQ} + \overrightarrow{QR} + \overrightarrow{RP} = \overrightarrow{PR} + \overrightarrow{RP} = \mathbf{0} \quad \text{Hence couple or equilibrium}$$

$$\begin{aligned} \sum \mathbf{r}_i \times \mathbf{F}_i &= (\mathbf{p} \times \overrightarrow{PQ}) + (\mathbf{q} \times \overrightarrow{QR}) + (\mathbf{r} \times \overrightarrow{RP}) \\ &= \mathbf{p} \times (\mathbf{q} - \mathbf{p}) + \mathbf{p} \times (\mathbf{r} - \mathbf{q}) + \mathbf{r} \times (\mathbf{p} - \mathbf{r}) \\ &= \mathbf{p} \times \mathbf{q} + \mathbf{q} \times \mathbf{r} + \mathbf{r} \times \mathbf{p} \end{aligned}$$

Hence system reduces to a couple of vector moment $(\mathbf{p} \times \mathbf{q}) + (\mathbf{q} \times \mathbf{r}) + (\mathbf{r} \times \mathbf{p})$

$$\text{d } \sum \mathbf{F}_i = \overrightarrow{AB} + \overrightarrow{BC} + \overrightarrow{CD} + \overrightarrow{DA} = \mathbf{0}$$

$$\begin{aligned} \sum \mathbf{r}_i \times \mathbf{F}_i &= \mathbf{a} \times \overrightarrow{AB} + \mathbf{b} \times \overrightarrow{BC} + \mathbf{c} \times \overrightarrow{CD} + \mathbf{d} \times \overrightarrow{DA} \\ &= \mathbf{a} \times (\mathbf{b} - \mathbf{a}) + \mathbf{b} \times (\mathbf{c} - \mathbf{b}) + \mathbf{c} \times (\mathbf{d} - \mathbf{c}) + \mathbf{d} \times (\mathbf{a} - \mathbf{d}) \\ &= \mathbf{a} \times \mathbf{b} + \mathbf{b} \times \mathbf{c} + \mathbf{c} \times \mathbf{d} + \mathbf{d} \times \mathbf{a} \end{aligned}$$

Hence system reduces to a couple of vector moment $(\mathbf{a} \times \mathbf{b} + \mathbf{b} \times \mathbf{c} + \mathbf{c} \times \mathbf{d} + \mathbf{d} \times \mathbf{a})$.

$$\text{e } \sum \mathbf{F}_i = \begin{pmatrix} 1 \\ 3 \\ 0 \end{pmatrix}$$

$$\begin{aligned} \sum \mathbf{r}_i \times \mathbf{F}_i &= \mathbf{0} + 3\mathbf{k} \\ &= \begin{pmatrix} 0 \\ 0 \\ 3 \end{pmatrix} \end{aligned}$$

$$\text{Since } \sum \mathbf{F}_i \cdot \sum \mathbf{r}_i \times \mathbf{F}_i = \begin{pmatrix} 1 \\ 3 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 0 \\ 3 \end{pmatrix} = 0 \text{ force is coplanar with the couple.}$$

Point on line of action given by

$$\mathbf{r} \times \begin{pmatrix} 1 \\ 3 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 3 \end{pmatrix} \quad \text{i.e.} \quad \begin{pmatrix} x \\ y \\ z \end{pmatrix} \times \begin{pmatrix} 1 \\ 3 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 3 \end{pmatrix}$$

$$\begin{pmatrix} -3z \\ z \\ 3x - y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 3 \end{pmatrix}$$

$$\Rightarrow z = 0, 3x - y = 3$$

$$\text{Let } x = 0, y = -3$$

$$\therefore \text{Equation of line of action is } \mathbf{r} = \begin{pmatrix} 0 \\ -3 \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ 3 \\ 0 \end{pmatrix}$$

Hence system reduces to a force $(\mathbf{i} + 3\mathbf{j})\text{N}$ acting at the point $(0, -3, 0)$.

Solutionbank M5

Edexcel AS and A Level Modular Mathematics

Exercise D, Question 7

Question:

$\mathbf{F}_1 = (3\mathbf{i} - \mathbf{j} + 2\mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_1 = (3\mathbf{i} - \mathbf{k})\text{m}$,

$\mathbf{F}_2 = (-\mathbf{i} - 4\mathbf{j} + \mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_2 = (2\mathbf{i} - 4\mathbf{j})\text{m}$,

$\mathbf{F}_3 = (\mathbf{i} + \mathbf{j} - 2\mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_3 = (-3\mathbf{j} + 5\mathbf{k})\text{m}$.

When a fourth force \mathbf{F}_4 is added the system is in equilibrium.

- a Find the force \mathbf{F}_4 .
- b Find a vector equation of its line of action.

Solution:

$$\begin{aligned} \mathbf{a} \quad \sum \mathbf{F}_i = \mathbf{0} &\Rightarrow \begin{pmatrix} 3 \\ -1 \\ 2 \end{pmatrix} + \begin{pmatrix} -1 \\ -4 \\ 1 \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} + \mathbf{F}_4 = \mathbf{0} \\ &\Rightarrow \mathbf{F}_4 = \begin{pmatrix} -3 \\ 4 \\ -1 \end{pmatrix} \text{ N} \end{aligned}$$

$$\text{i.e. } \mathbf{F}_4 = (-3\mathbf{i} + 4\mathbf{j} - \mathbf{k})\text{N}$$

$$\begin{aligned} \mathbf{b} \quad \sum \mathbf{r}_i \times \mathbf{F}_i &= \begin{pmatrix} 3 \\ 0 \\ -1 \end{pmatrix} \times \begin{pmatrix} 3 \\ -1 \\ 2 \end{pmatrix} + \begin{pmatrix} 2 \\ -4 \\ 0 \end{pmatrix} \times \begin{pmatrix} -1 \\ -4 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ -3 \\ 5 \end{pmatrix} \times \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} + \mathbf{r} \times \begin{pmatrix} -3 \\ 4 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \\ \begin{pmatrix} -1 \\ -9 \\ -3 \end{pmatrix} + \begin{pmatrix} -4 \\ -2 \\ -12 \end{pmatrix} + \begin{pmatrix} 1 \\ 5 \\ 3 \end{pmatrix} + \mathbf{r} \times \begin{pmatrix} -3 \\ 4 \\ -1 \end{pmatrix} &= \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \\ \begin{pmatrix} -4 \\ -6 \\ -12 \end{pmatrix} + \mathbf{r} \times \begin{pmatrix} -3 \\ 4 \\ -1 \end{pmatrix} &= \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \\ \Rightarrow \begin{pmatrix} x \\ y \\ z \end{pmatrix} \times \begin{pmatrix} -3 \\ 4 \\ -1 \end{pmatrix} &= \begin{pmatrix} 4 \\ 6 \\ 12 \end{pmatrix} \\ \Rightarrow \begin{pmatrix} -y-4z \\ -3z+x \\ 4x+3y \end{pmatrix} &= \begin{pmatrix} 4 \\ 6 \\ 12 \end{pmatrix} \\ \Rightarrow -y-4z &= 4 \\ -3z+x &= 6 \\ 4x+3y &= 12 \end{aligned}$$

Let $x=0 \Rightarrow y=4$ and $z=-2$

\therefore Equation of line of action is

$$\mathbf{r} = \begin{pmatrix} 0 \\ 4 \\ -2 \end{pmatrix} + \lambda \begin{pmatrix} -3 \\ 4 \\ -1 \end{pmatrix}$$

Solutionbank M5

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Exercise D, Question 8

Question:

A force $(\mathbf{i} - \mathbf{j} + 2\mathbf{k})\text{N}$ acts through the point $(-1, -1, 1)$. Show that this force is equivalent to an equal force acting through the origin together with a couple. Find the magnitude of this couple.

Solution:

$$\begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix} \times \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} = \mathbf{O} + \mathbf{G}, \text{ comparing moments about } O.$$

$$\begin{pmatrix} -1 \\ 3 \\ 2 \end{pmatrix} = \mathbf{G} \text{ so } |\mathbf{G}| = \sqrt{(-1)^2 + 3^2 + 2^2}$$

$$= \sqrt{14} \text{ Nm}$$

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Exercise D, Question 9

Question:

Prove that the following system of forces can be reduced to a force together with a non-coplanar couple.

$\mathbf{F}_1 = (\mathbf{i} + \mathbf{j})\text{N}$ acting at the point with position vector $\mathbf{r}_1 = (3\mathbf{i} + \mathbf{j} + \mathbf{k})\text{ m}$,

$\mathbf{F}_2 = (\mathbf{i} + \mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_2 = \mathbf{i}\text{ m}$,

$\mathbf{F}_3 = (2\mathbf{j} - \mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_3 = 2\mathbf{j}\text{ m}$.

Solution:

$$\sum \mathbf{F}_i = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ 2 \\ -1 \end{pmatrix} = \begin{pmatrix} 2 \\ 3 \\ 0 \end{pmatrix}$$

$$\sum \mathbf{r}_i \times \mathbf{F}_i = \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix} \times \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \times \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 2 \\ -1 \end{pmatrix}$$

$$= \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix} + \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix} + \begin{pmatrix} -2 \\ 0 \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} -3 \\ 0 \\ 2 \end{pmatrix}$$

$$\sum \mathbf{F}_i \cdot \sum \mathbf{r}_i \times \mathbf{F}_i = \begin{pmatrix} 2 \\ 3 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} -3 \\ 0 \\ 2 \end{pmatrix} = -6 \neq 0$$

Hence, resultant force is *not* coplanar with couple.

So system can be reduced to a force $(2\mathbf{i} + 3\mathbf{j})\text{N}$ acting through the origin O together with a couple of vector moment $(-3\mathbf{i} + 2\mathbf{k})\text{Nm}$.

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Exercise D, Question 10

Question:

A force $(\mathbf{i} + 2\mathbf{j} - \mathbf{k})\text{N}$ acts through the point $(2, 0, 0)$ together with a couple of vector moment $(2\mathbf{i} - \mathbf{k})\text{Nm}$.

- a Show that this system cannot be reduced.
- b Find an equivalent system where the force acts through the point $(1, -3, 4)$.

Solution:

$$\mathbf{a} \quad \sum \mathbf{F}_i = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}$$

$$\begin{aligned} \sum \mathbf{r}_i \times \mathbf{F}_i &= \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix} \times \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} + \begin{pmatrix} 2 \\ 0 \\ -1 \end{pmatrix} \\ &= \begin{pmatrix} 0 \\ 2 \\ 4 \end{pmatrix} + \begin{pmatrix} 2 \\ 0 \\ -1 \end{pmatrix} \\ &= \begin{pmatrix} 2 \\ 2 \\ 3 \end{pmatrix} \end{aligned}$$

$$\sum \mathbf{F}_i \cdot \sum \mathbf{r}_i \times \mathbf{F}_i = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 2 \\ 3 \end{pmatrix} = 3 \neq 0$$

Hence, resultant force is non-coplanar with the couple \therefore no further reduction possible.

$$\mathbf{b} \quad \text{Force } \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} \text{ at } (2, 0, 0) + \text{Couple } \begin{pmatrix} 2 \\ 0 \\ -1 \end{pmatrix} \equiv \text{Force } \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} \text{ at } (1, -3, 4) + \text{Couple } \mathbf{G}$$

$$(2, 0, 0) \quad (1, -3, 4)$$

Comparing moments about O ,

From **a**,

$$\begin{pmatrix} 2 \\ 2 \\ 3 \end{pmatrix} = \begin{pmatrix} 1 \\ -3 \\ 4 \end{pmatrix} \times \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} + \mathbf{G}$$

$$\begin{pmatrix} 2 \\ 2 \\ 3 \end{pmatrix} = \begin{pmatrix} -5 \\ 5 \\ 5 \end{pmatrix} + \mathbf{G}$$

$$\begin{pmatrix} 7 \\ -3 \\ -2 \end{pmatrix} = \mathbf{G}$$

Equivalent system is $(\mathbf{i} + 2\mathbf{j} - \mathbf{k})\text{N}$ acting at $(1, -3, 4)$ plus a couple of moment $(7\mathbf{i} - 3\mathbf{j} - 2\mathbf{k})\text{Nm}$

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Exercise E, Question 1

Question:

The vertices of a tetrahedron $PQRS$ have position vectors \mathbf{p} , \mathbf{q} , \mathbf{r} and \mathbf{s} respectively, where

$$\mathbf{p} = 3\mathbf{i} - 4\mathbf{j} + \mathbf{k} \quad \mathbf{q} = 4\mathbf{i} + 4\mathbf{j} - 2\mathbf{k}$$

$$\mathbf{r} = 4\mathbf{i} + \mathbf{k} \quad \mathbf{s} = \mathbf{i} - 2\mathbf{j} + \mathbf{k}$$

Forces of magnitude 30 and $\sqrt{117}$ act along RQ and RS respectively. A third force acts at P . Given that the system reduces to a couple,

- a** find the magnitude of this couple,
- b** find the force acting at P ,
- c** find a unit vector along the axis of the couple.

Solution:

Find the third force \mathbf{F}_3 first.

$$\mathbf{a} \quad \overrightarrow{RQ} = \mathbf{q} - \mathbf{r} = \begin{pmatrix} 4 \\ 4 \\ -2 \end{pmatrix} - \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 4 \\ -3 \end{pmatrix}$$

$$\mathbf{F}_1 = \frac{1}{5} \begin{pmatrix} 0 \\ 4 \\ -3 \end{pmatrix} \times 30 = \begin{pmatrix} 0 \\ 24 \\ -18 \end{pmatrix}$$

$$\overrightarrow{RS} = \mathbf{s} - \mathbf{r} = \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix} - \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -3 \\ -2 \\ 0 \end{pmatrix}$$

$$\mathbf{F}_2 = \frac{1}{\sqrt{13}} \begin{pmatrix} -3 \\ -2 \\ 0 \end{pmatrix} \sqrt{117} = \frac{1}{\sqrt{13}} \begin{pmatrix} -3 \\ -2 \\ 0 \end{pmatrix} 3\sqrt{13} = \begin{pmatrix} -9 \\ -6 \\ 0 \end{pmatrix}$$

$$\sum \mathbf{F}_i = \begin{pmatrix} 0 \\ 24 \\ -18 \end{pmatrix} + \begin{pmatrix} -9 \\ -6 \\ 0 \end{pmatrix} + \mathbf{F}_3 = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \mathbf{F}_3 = \begin{pmatrix} 9 \\ -18 \\ 18 \end{pmatrix}$$

Sum of moments about R :

$$\begin{aligned} \overrightarrow{RP} \times \begin{pmatrix} 9 \\ -18 \\ 18 \end{pmatrix} &= \left\{ \begin{pmatrix} 3 \\ -4 \\ 1 \end{pmatrix} - \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix} \right\} \times \begin{pmatrix} 9 \\ -18 \\ 18 \end{pmatrix} = \begin{pmatrix} -1 \\ -4 \\ 0 \end{pmatrix} \times \begin{pmatrix} 9 \\ -18 \\ 18 \end{pmatrix} \\ &= \begin{pmatrix} -72 \\ 18 \\ 54 \end{pmatrix} = 18 \begin{pmatrix} -4 \\ 1 \\ 3 \end{pmatrix} \end{aligned}$$

$$\therefore \text{Magnitude} = 18\sqrt{26} \text{ Nm}$$

$$\mathbf{b} \quad \begin{pmatrix} 9 \\ -18 \\ 18 \end{pmatrix}$$

$$\mathbf{c} \quad \text{unit vector along axis} \quad \frac{1}{\sqrt{26}} \begin{pmatrix} -4 \\ 1 \\ 3 \end{pmatrix}$$

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Exercise E, Question 2

Question:

Two forces $(3\mathbf{i} + 2\mathbf{j} + \mathbf{k})\text{N}$ and $(\mathbf{i} + 2\mathbf{j} + 3\mathbf{k})\text{N}$ act at the points $D(4, -1, 1)$ and $E(3, 1, 6)$ respectively.

- Find the force through the origin O and the couple which together are equivalent to these two forces.
- Find the magnitude of the couple.
- Show that the lines of action of the forces through D and E meet and find the position vector of the point of intersection.

Solution:

$$\mathbf{a} \quad \sum \mathbf{F}_i = \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} + \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} = \begin{pmatrix} 4 \\ 4 \\ 4 \end{pmatrix}$$

$$\begin{aligned} \sum \mathbf{r}_i \times \mathbf{F}_i &= \begin{pmatrix} 4 \\ -1 \\ 1 \end{pmatrix} \times \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} + \begin{pmatrix} 3 \\ 1 \\ 6 \end{pmatrix} \times \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} = \begin{pmatrix} -3 \\ -1 \\ 11 \end{pmatrix} + \begin{pmatrix} -9 \\ -3 \\ 5 \end{pmatrix} \\ &= \begin{pmatrix} -12 \\ -4 \\ 16 \end{pmatrix} = \mathbf{G} \end{aligned}$$

Hence force is $(4\mathbf{i} + 4\mathbf{j} + 4\mathbf{k})\text{N}$ through O plus a couple of vector moment $(-12\mathbf{i} - 4\mathbf{j} + 16\mathbf{k})\text{Nm}$.

$$\mathbf{b} \quad |\mathbf{G}| = 4\sqrt{(-3)^2 + (-1)^2 + 4^2} = 4\sqrt{26} \text{ Nm}$$

$$\begin{aligned} \mathbf{c} \quad \begin{pmatrix} 4 \\ -1 \\ 1 \end{pmatrix} + \lambda \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} &= \begin{pmatrix} 3 \\ 1 \\ 6 \end{pmatrix} + \mu \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \\ \Rightarrow 4 + 3\lambda &= 3 + \mu & \text{①} \\ -1 + 2\lambda &= 1 + 2\mu & \text{②} \\ 1 + \lambda &= 6 + 3\mu & \text{③} \\ \text{②} - \text{①}: 0 + 3\lambda &= 7 + 5\mu & \text{④} \\ \text{①} - \text{④}: 4 &= -4 - 4\mu \\ -2 &= \mu \Rightarrow \lambda = -1 \end{aligned}$$

Point of intersection has position vector $(\mathbf{i} - 3\mathbf{j})\text{m}$.

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Exercise E, Question 3

Question:

A system of five forces consists of the forces $\mathbf{F}_1 = (\mathbf{i} - 2\mathbf{j} + 2\mathbf{k})\text{N}$, $\mathbf{F}_2 = (2\mathbf{i} + 6\mathbf{k})\text{N}$ and $\mathbf{F}_3 = (\mathbf{i} - 2\mathbf{j} - 4\mathbf{k})\text{N}$, all acting through the origin O , together with a force $\mathbf{F}_4 = (\mathbf{i} - 2\mathbf{j} - \mathbf{k})\text{N}$ acting through the point $(-2, 4, 2)$ and a force $\mathbf{F}_5 = (-\mathbf{i} - 2\mathbf{j} - 7\mathbf{k})\text{N}$ acting through the point $(1, -2, -1)$.

- Reduce the system to a force \mathbf{R} acting at O together with a couple \mathbf{G} .
- Hence, or otherwise, verify that the system is equivalent to a single force $(4\mathbf{i} - 8\mathbf{j} - 4\mathbf{k})\text{N}$ acting through the point $(1, -1, 1)$.

Solution:

$$\mathbf{a} \quad \mathbf{R} = \sum \mathbf{F}_i = \begin{pmatrix} 1 \\ -2 \\ 2 \end{pmatrix} + \begin{pmatrix} 2 \\ 0 \\ 6 \end{pmatrix} + \begin{pmatrix} 1 \\ -2 \\ -4 \end{pmatrix} + \begin{pmatrix} 1 \\ -2 \\ -1 \end{pmatrix} + \begin{pmatrix} -1 \\ -2 \\ -7 \end{pmatrix} = \begin{pmatrix} 4 \\ -8 \\ -4 \end{pmatrix}$$

$$\begin{aligned} \mathbf{G} = \sum \mathbf{r}_i \times \mathbf{F}_i &= \begin{pmatrix} -2 \\ 4 \\ 2 \end{pmatrix} \times \begin{pmatrix} 1 \\ -2 \\ -1 \end{pmatrix} + \begin{pmatrix} 1 \\ -2 \\ -1 \end{pmatrix} \times \begin{pmatrix} -1 \\ -2 \\ -7 \end{pmatrix} \\ &= \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 12 \\ 8 \\ -4 \end{pmatrix} \\ &= \begin{pmatrix} 12 \\ 8 \\ -4 \end{pmatrix} \end{aligned}$$

$$\mathbf{R} = (4\mathbf{i} - 8\mathbf{j} - 4\mathbf{k})\text{N}, \mathbf{G} = (12\mathbf{i} + 8\mathbf{j} - 4\mathbf{k})\text{Nm}$$

$$\mathbf{b} \quad \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \times \begin{pmatrix} 4 \\ -8 \\ -4 \end{pmatrix} = \begin{pmatrix} 12 \\ 8 \\ -4 \end{pmatrix} = \mathbf{G} \quad \text{QED}$$

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Exercise E, Question 4

Question:

A system consists of three forces:

$\mathbf{F}_1 = (\mathbf{i} - \mathbf{j} + 2\mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_1 = (3\mathbf{i} - \mathbf{j} + \mathbf{k})\text{ m}$,

$\mathbf{F}_2 = (\mathbf{i} + 3\mathbf{j} - \mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_2 = (\mathbf{j} + 2\mathbf{k})\text{ m}$,

$\mathbf{F}_3 = (s\mathbf{i} + t\mathbf{j} + 2\mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_3 = \mathbf{k}\text{ m}$.

- Obtain, in terms of s and t , the equivalent system consisting of a single force \mathbf{F} acting through the origin and a couple of moment \mathbf{G} .
- Determine the values of s and t such that \mathbf{G} is parallel to \mathbf{F} .

Solution:

$$\begin{aligned} \mathbf{a} \quad \sum \mathbf{F}_i &= \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} + \begin{pmatrix} 1 \\ 3 \\ -1 \end{pmatrix} + \begin{pmatrix} s \\ t \\ 2 \end{pmatrix} \\ &= \begin{pmatrix} 2+s \\ 2+t \\ 3 \end{pmatrix} = \mathbf{F} \end{aligned}$$

$$\begin{aligned} \sum \mathbf{r}_i \times \mathbf{F}_i &= \begin{pmatrix} 3 \\ -1 \\ 1 \end{pmatrix} \times \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix} \times \begin{pmatrix} 1 \\ 3 \\ -1 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \times \begin{pmatrix} s \\ t \\ 2 \end{pmatrix} \\ &= \begin{pmatrix} -1 \\ -5 \\ -2 \end{pmatrix} + \begin{pmatrix} -7 \\ 2 \\ -1 \end{pmatrix} + \begin{pmatrix} -t \\ s \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} -8-t \\ -3+s \\ -3 \end{pmatrix} = \mathbf{G} \end{aligned}$$

$$\begin{aligned} \mathbf{b} \quad \mathbf{G} \text{ parallel to } \mathbf{F} &\Rightarrow -(2+s) = -8-t \Rightarrow 6 = s-t \\ &\quad -(2+t) = -3+s \Rightarrow 1 = s+t \\ &\quad \Rightarrow s = \frac{7}{2}; t = \frac{-5}{2} \end{aligned}$$

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Exercise E, Question 5

Question:

A force \mathbf{F}_1 of magnitude 26 N, acts along the direction of the vector $(4\mathbf{i} - 3\mathbf{j} + 12\mathbf{k})$.

Given that the line of action of \mathbf{F}_1 passes through the point $(2, 1, -1)$,

a find the moment of \mathbf{F}_1 about O .

A bead moves along a smooth straight wire from the point $P(3, -2, 1)$ to the point $Q(5, -22, 2)$, under the influence of \mathbf{F}_1 and the reaction from the wire only.

b Find the work done by \mathbf{F}_1 in this motion.

Solution:

$$\begin{aligned} \mathbf{a} \quad \mathbf{F}_1 &= \frac{1}{13} \begin{pmatrix} 4 \\ -3 \\ 12 \end{pmatrix} \times 26 = \begin{pmatrix} 8 \\ -6 \\ 24 \end{pmatrix} \\ \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix} \times \begin{pmatrix} 8 \\ -6 \\ 24 \end{pmatrix} &= \begin{pmatrix} 18 \\ -56 \\ -20 \end{pmatrix} \text{ Nm} = (18\mathbf{i} - 56\mathbf{j} - 20\mathbf{k}) \text{ Nm} \end{aligned}$$

$$\begin{aligned} \mathbf{b} \quad \overrightarrow{PQ} &= \begin{pmatrix} 2 \\ -20 \\ 1 \end{pmatrix} \\ \text{work done} &= \begin{pmatrix} 8 \\ -6 \\ 24 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ -20 \\ 1 \end{pmatrix} = 16 + 120 + 24 = 160 \text{ J} \end{aligned}$$

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Exercise E, Question 6

Question:

A system consists of three forces:

$\mathbf{F}_1 = (4\mathbf{i} + \mathbf{j} + 2\mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_1 = (6\mathbf{i} + 4\mathbf{j} + \mathbf{k})\text{ m}$,

$\mathbf{F}_2 = (\mathbf{i} - 2\mathbf{j} + \mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_2 = (\mathbf{i} + 5\mathbf{j} - 2\mathbf{k})\text{ m}$,

$\mathbf{F}_3 = (-5\mathbf{i} + \mathbf{j} - 3\mathbf{k})\text{N}$ acting at the point with position vector $\mathbf{r}_3 = (\mathbf{i} + \mathbf{j} + \mathbf{k})\text{ m}$.

a Show that this system reduces to a couple and find its magnitude.

The force \mathbf{F}_3 is now removed from the system and replaced by the force \mathbf{F}_4 such that the forces $\mathbf{F}_1, \mathbf{F}_2$ and \mathbf{F}_4 are in equilibrium. Find

b the magnitude of \mathbf{F}_4 ,

c a vector equation for the line of action of \mathbf{F}_4 .

Solution:

$$\begin{aligned} \mathbf{a} \quad \sum \mathbf{F}_i &= \begin{pmatrix} 4 \\ 1 \\ 2 \end{pmatrix} + \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix} + \begin{pmatrix} -5 \\ 1 \\ -3 \end{pmatrix} \\ &= \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \sum \mathbf{r}_i \times \mathbf{F}_i &= \begin{pmatrix} 6 \\ 4 \\ 1 \end{pmatrix} \times \begin{pmatrix} 4 \\ 1 \\ 2 \end{pmatrix} + \begin{pmatrix} 1 \\ 5 \\ -2 \end{pmatrix} \times \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \times \begin{pmatrix} -5 \\ 1 \\ -3 \end{pmatrix} \\ &= \begin{pmatrix} 7 \\ -8 \\ -10 \end{pmatrix} + \begin{pmatrix} 1 \\ -3 \\ -7 \end{pmatrix} + \begin{pmatrix} -4 \\ -2 \\ 6 \end{pmatrix} \\ &= \begin{pmatrix} 4 \\ -13 \\ -11 \end{pmatrix} = \mathbf{G} \end{aligned}$$

$$|\mathbf{G}| = \sqrt{4^2 + (-13)^2 + (-11)^2} = \sqrt{16 + 169 + 121} = \sqrt{306} \text{ Nm}$$

$$\mathbf{b} \quad \begin{pmatrix} 4 \\ 1 \\ 2 \end{pmatrix} + \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix} + \mathbf{F}_4 = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\mathbf{F}_4 = \begin{pmatrix} -5 \\ 1 \\ -3 \end{pmatrix} \Rightarrow |\mathbf{F}_4| = \sqrt{25 + 1 + 9} = \sqrt{35} \text{ N}$$

\mathbf{c} From \mathbf{a} ,

$$\begin{aligned} \sum \mathbf{r}_i \times \mathbf{F}_1 &= \begin{pmatrix} 7 \\ -8 \\ -10 \end{pmatrix} + \begin{pmatrix} 1 \\ -3 \\ -7 \end{pmatrix} + \mathbf{r} \times \begin{pmatrix} -5 \\ 1 \\ -3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \\ &\Rightarrow \begin{pmatrix} x \\ y \\ z \end{pmatrix} \times \begin{pmatrix} -5 \\ 1 \\ -3 \end{pmatrix} = \begin{pmatrix} -8 \\ 11 \\ 17 \end{pmatrix} \\ &\quad \begin{pmatrix} -3y - z \\ -5z + 3x \\ x + 5y \end{pmatrix} = \begin{pmatrix} -8 \\ 11 \\ 17 \end{pmatrix} \end{aligned}$$

Put $y = 0$: $x = 17, z = 8$

$$\text{Equation of line of action of } \mathbf{F}_4 \text{ is } \mathbf{r} = \begin{pmatrix} 17 \\ 0 \\ 8 \end{pmatrix} + \lambda \begin{pmatrix} -5 \\ 1 \\ -3 \end{pmatrix}$$

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Exercise E, Question 7

Question:

Three forces of magnitudes 26, $4\sqrt{41}$ and 15 N act respectively along the sides OP , PQ and QO of the triangle POQ where O is the origin. Relative to O , the coordinates of P and Q are $(5, 12, 0)$ and $(3, 0, 4)$ respectively.

- Show that the resultant is $(-3\mathbf{i} - 4\mathbf{k})\text{N}$.
- Find the magnitude of the moment of the resultant about O .

Solution:

$$\mathbf{a} \quad \mathbf{F}_1 = \frac{1}{13} \begin{pmatrix} 5 \\ 12 \\ 0 \end{pmatrix} \times 26 = \begin{pmatrix} 10 \\ 24 \\ 0 \end{pmatrix} \text{ N}$$

$$\overrightarrow{PQ} = \begin{pmatrix} 3 \\ 0 \\ 4 \end{pmatrix} - \begin{pmatrix} 5 \\ 12 \\ 0 \end{pmatrix} = \begin{pmatrix} -2 \\ -12 \\ 4 \end{pmatrix}$$

$$\mathbf{F}_2 = \frac{1}{\sqrt{(-2)^2 + (-12)^2 + 4^2}} \begin{pmatrix} -2 \\ -12 \\ 4 \end{pmatrix} \cdot 4\sqrt{41}$$

$$= \frac{1}{\sqrt{164}} \begin{pmatrix} -2 \\ -12 \\ 4 \end{pmatrix} 4\sqrt{41} = \begin{pmatrix} -4 \\ -24 \\ 8 \end{pmatrix} \text{ N}$$

$$\overrightarrow{QO} = \begin{pmatrix} -3 \\ 0 \\ -4 \end{pmatrix}$$

$$\mathbf{F}_3 = \frac{1}{5} \begin{pmatrix} -3 \\ 0 \\ -4 \end{pmatrix} \cdot 15 = \begin{pmatrix} -9 \\ 0 \\ -12 \end{pmatrix} \text{ N}$$

$$\sum \mathbf{F}_i = \begin{pmatrix} 10 \\ 24 \\ 0 \end{pmatrix} + \begin{pmatrix} -4 \\ -24 \\ 8 \end{pmatrix} + \begin{pmatrix} -9 \\ 0 \\ -12 \end{pmatrix} = \begin{pmatrix} -3 \\ 0 \\ -4 \end{pmatrix} = (-3\mathbf{i} - 4\mathbf{k})\text{N}$$

$$\mathbf{b} \quad \sum \mathbf{r}_i \times \mathbf{F}_i = \begin{pmatrix} 5 \\ 12 \\ 0 \end{pmatrix} \times \begin{pmatrix} -4 \\ -24 \\ 8 \end{pmatrix} = \begin{pmatrix} 96 \\ -40 \\ -72 \end{pmatrix} = \mathbf{G}$$

$$|\mathbf{G}| = 8\sqrt{12^2 + (-5)^2 + (-9)^2}$$

$$= 8\sqrt{144 + 25 + 81}$$

$$= 8\sqrt{250}$$

$$= 40\sqrt{10} \text{ Nm}$$

Solutionbank M5

Edexcel AS and A Level Modular Mathematics

Exercise E, Question 8

Question:

The point A has coordinates $(2, -5, 1)$, the point B has coordinates $(-8, -1, 4)$, the point C has coordinates $(0, -13, 5)$ and the point D has coordinates $(4, 3, -3)$.

- a Show that the lines AB and CD intersect at right angles.
- b Find the coordinates of the point of intersection.

A force of magnitude F acting in the direction AD moves a particle from B to D .

- c Find the work done by the force.

Solution:

$$\begin{aligned} \text{a } \overrightarrow{AB} &= \begin{pmatrix} -8-2 \\ -1+5 \\ 4-1 \end{pmatrix} = \begin{pmatrix} -10 \\ 4 \\ 3 \end{pmatrix} \\ \overrightarrow{CD} &= \begin{pmatrix} 4-0 \\ 3+13 \\ -3-5 \end{pmatrix} = \begin{pmatrix} 4 \\ 16 \\ -8 \end{pmatrix} \\ \overrightarrow{AB} \cdot \overrightarrow{CD} &= \begin{pmatrix} -10 \\ 4 \\ 3 \end{pmatrix} \cdot \begin{pmatrix} 4 \\ 16 \\ -8 \end{pmatrix} = -40 + 64 - 24 = 0 \\ \therefore &\text{ perpendicular} \end{aligned}$$

$$\begin{aligned} \text{b } \begin{pmatrix} 2 \\ -5 \\ 1 \end{pmatrix} + \lambda \begin{pmatrix} -10 \\ 4 \\ 3 \end{pmatrix} &= \begin{pmatrix} 0 \\ -13 \\ 5 \end{pmatrix} + \mu \begin{pmatrix} 4 \\ 16 \\ -8 \end{pmatrix} \\ \Rightarrow 2 - 10\lambda &= 4\mu & \text{①} \\ -5 + 4\lambda &= -13 + 16\mu & \text{②} \\ 1 + 3\lambda &= 5 - 8\mu & \text{③} \\ 2 + 6\lambda &= 10 - 16\mu & \text{③} \times 3 \\ -3 + 10\lambda &= -3 \\ \lambda = 0 &\Rightarrow \mu = \frac{1}{2} \end{aligned}$$

Point of intersection is $(2, -5, 1)$

$$\text{c } \mathbf{F} = F \times \text{unit vector along } \overrightarrow{AD}$$

$$\begin{aligned} \overrightarrow{AD} &= \begin{pmatrix} 2 \\ 8 \\ -4 \end{pmatrix} \quad |\overrightarrow{AD}| = \sqrt{2^2 + 8^2 + (-4)^2} \\ &= \sqrt{4 + 64 + 16} \\ &= \sqrt{84} \end{aligned}$$

$$\text{So, } \mathbf{F} = \frac{F}{\sqrt{84}} \begin{pmatrix} 2 \\ 8 \\ -4 \end{pmatrix}; \quad \overrightarrow{BD} = \begin{pmatrix} 4+8 \\ 3+1 \\ -3-4 \end{pmatrix} = \begin{pmatrix} 12 \\ 4 \\ -7 \end{pmatrix}$$

$$\begin{aligned} \text{work done} &= \frac{F}{\sqrt{84}} \begin{pmatrix} 2 \\ 8 \\ -4 \end{pmatrix} \cdot \begin{pmatrix} 12 \\ 4 \\ -7 \end{pmatrix} \\ &= \frac{F}{\sqrt{84}} (24 + 32 + 28) = F\sqrt{84} = 2F\sqrt{21} \end{aligned}$$

Solutionbank M5

Edexcel AS and A Level Modular Mathematics

Exercise E, Question 9

Question:

The force $\mathbf{F} = (x\mathbf{i} + y\mathbf{j})\text{N}$ acts through the point with position vector $\mathbf{r} = (xi - yj)\text{ m}$.

- a** Prove that this force is equivalent to an equal force at O together with a couple.

Three variable forces $\mathbf{F}_1 = 2\cos t\mathbf{i}$, $\mathbf{F}_2 = \cos t\mathbf{i} + 2\sin t\mathbf{j}$, $\mathbf{F}_3 = 3\sin t\mathbf{i} + \cos t\mathbf{j}$ act at the points with position vectors \mathbf{O} , $\mathbf{i} + \mathbf{j}$ and $-3\mathbf{i} + 2\mathbf{j}$ respectively.

If the system is reduced to a single force \mathbf{R} acting at O with a couple \mathbf{G} ,

- b** find the values of \mathbf{R} and \mathbf{G} .
c reduce an equation of the line of action of the resultant.
d Show that this line passes through a fixed point which is independent of t .

Solution:

$$\mathbf{a} \quad \begin{pmatrix} x \\ -y \\ 0 \end{pmatrix} \times \begin{pmatrix} X \\ Y \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ xY + yX \end{pmatrix} = \mathbf{G}$$

Couple is $(xY + yX)\mathbf{k}$ Nm.

$$\mathbf{b} \quad \mathbf{R} = \sum \mathbf{F}_i = \begin{pmatrix} 2\cos t \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} \cos t \\ 2\sin t \\ 0 \end{pmatrix} + \begin{pmatrix} 3\sin t \\ \cos t \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} 3\cos t + 3\sin t \\ 2\sin t + \cos t \\ 0 \end{pmatrix} \text{ N}$$

$$\mathbf{G} = \sum \mathbf{r}_i \times \mathbf{F}_i = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \times \begin{pmatrix} \cos t \\ 2\sin t \\ 0 \end{pmatrix} + \begin{pmatrix} -3 \\ 2 \\ 0 \end{pmatrix} \times \begin{pmatrix} 3\sin t \\ \cos t \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} 0 \\ 0 \\ 2\sin t - \cos t \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ -3\cos t - 6\sin t \end{pmatrix}$$

$$= \begin{pmatrix} 0 \\ 0 \\ -4\sin t - 4\cos t \end{pmatrix}$$

$$\mathbf{c} \quad \begin{pmatrix} x \\ y \\ z \end{pmatrix} \times \begin{pmatrix} 3\cos t + 3\sin t \\ 2\sin t + \cos t \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -4\sin t - 4\cos t \end{pmatrix}$$

$$\begin{pmatrix} -z(2\sin t + \cos t) \\ z(3\cos t + 3\sin t) \\ x(2\sin t + \cos t) - y(3\cos t + 3\sin t) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -4\sin t - 4\cos t \end{pmatrix}$$

$$\Rightarrow 2x - 3y = -4; x - 3y = -4; z = 0$$

If $x = 0, y = \frac{4}{3}, z = 0$ (\forall (for all) t)

Hence line of action is $\mathbf{r} = \begin{pmatrix} 0 \\ \frac{4}{3} \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} 3\cos t + 3\sin t \\ 2\sin t + \cos t \\ 0 \end{pmatrix}$

\mathbf{d} This line passes through the fixed point $\begin{pmatrix} 0 \\ \frac{4}{3} \\ 0 \end{pmatrix}$ which is independent of t .

Solutionbank M5

Edexcel AS and A Level Modular Mathematics

Exercise E, Question 10

Question:

A force of unit magnitude has equal vector moments about points with position vectors \mathbf{j} m and $(\mathbf{i} + 2\mathbf{j} - \mathbf{k})$ m. Find the possible forces.

Solution:

$$\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \times \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} \times \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix} \times \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \mathbf{0}$$

$$\Rightarrow \begin{pmatrix} -z - y \\ x + z \\ -y + x \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow y = -z$$

$$x = -z$$

$$\Rightarrow x = y = -z$$

$$\text{and } x^2 + y^2 + z^2 = 1$$

$$3x^2 = 1$$

$$x = \pm \frac{1}{\sqrt{3}}$$

$$x = \frac{1}{\sqrt{3}}; y = \frac{1}{\sqrt{3}}; z = -\frac{1}{\sqrt{3}}$$

$$x = \frac{-1}{\sqrt{3}}; y = \frac{-1}{\sqrt{3}}; z = \frac{1}{\sqrt{3}}$$

$$\text{Possible forces } \pm \frac{1}{\sqrt{3}}(\mathbf{i} + \mathbf{j} - \mathbf{k})\text{N}$$